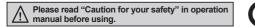
Modbus Sensor Connector Type Digital Remote I/O

Features

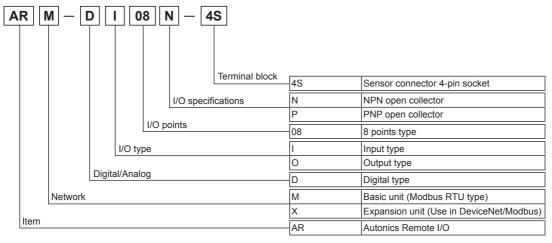
- Modbus RTU standard protocol
- Connects with sensor connector, e-CON: saves wiring work (sensor connector, CNE Series, sold separately)
- Compact size
- : Small size with W26×L76×H54mm to install at narrow space
- : Available DIN Rail mounting and screw lock mounting method
- Real-time monitoring by various functions
- : Communication speed auto-recognition,
- Network power voltage monitoring
- : Reading number of expansion units and specifications, Reading model name of basic and expansion units
- : Monitoring Single byte input/output, Multi byte input/output and status Flag
- Easy expansion
- : Available to connect up to 63 basic units per 1 master unit
- : Available to connect up to 7 expansion units per 1 basic units (controllable input/output for max. 64 points)
- : Combines the desired specifications of input/output by various input/output units
- : Organizes power and communication system by only communication cable lines
- High reliability
- : Built-in surge, short, over-heat, reverse power polarity and static prevention circuits



User Manual For Communication

- Visit our website (www.autonics.com) to download the user manual for communication for Modbus communication.
- The user manual for communication describes for Modbus RTU protocol, Modbus Mapping Table.

Ordering Information



Model

Model		Specification	
Basic unit	Expansion unit	Specification	
ARM-DI08N-4S	ARX-DI08N-4S	10-28VDC NPN input 8-point (10mA/point)	
ARM-DI08P-4S	ARX-DI08P-4S	10-28VDC PNP input 8-point (10mA/point)	
ARM-DO08N-4S	ARX-DO08N-4S	10-28VDC NPN output 8-point (0.3mA/point)	
ARM-DO08P-4S	ARX-D008P-4S	10-28VDC PNP output 8-point (0.3mA/point)	



(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

Graphic/ Logic Panels

Field Network Devices

> 「) oftware

Autonics S-23

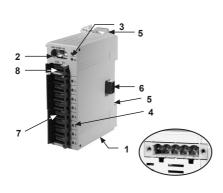
Specifications

Model -	Basic unit	ARM-DI08N-4S	ARM-DI08P-4S	ARM-DO08N-4S	ARM-DO08P-4S		
	Expansion unit	ARX-DI08N-4S	ARX-DI08P-4S	ARX-DO08N-4S	ARX-DO08P-4S		
ower	supply	Rated voltage: 24VDC, Vo	Itage range: 12-28VDC				
ower	consumption	Max. 3W					
I/O points		NPN input 8 points	PNP input 8 points	NPN output 8 points	PNP output 8 points		
Control I/O	Voltage	10-28VDC Output (voltage drop: Max. 0.5V)					
	Current	10mA/point (sensor current: 150mA/points) 0.3A/point (leakage current: Max. 0.5mA)			nt: Max. 0.5mA)		
	COMMON method	8 points, common					
rotoco	l	Modbus RTU					
Media access		POLL					
Applica	tion standard	Compliance with EIA RS485					
Commi	inication method	2-wire half duplex					
Commu	inication distance	Max. 800m					
√ulti-dr	ор	Max. 32 Multi-Drop					
Data bi	t	8 bits					
Commu	inication speed	2400, 4800, 9600, 19200, 38400, 57600, 115200bps (default 9600bps)					
Stop bit		1 or 2 bits (default: 2)					
Parity bit		None/Odd/Even (default: None)					
Insulation resistance		Min. $200M\Omega$ (at $500VDC$ megger)					
Noise resistance		±240V the square wave noise (pulse width: 1μs) by the noise simulator					
Dielectric strength		1,000VAC 50/60Hz for 1 minute					
Vibration		1.5mm amplitude or 300m/s² at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for 2 hours					
Shock		500m/s² (approx. 50G) in each of X, Y, Z directions for3 times					
Environ	Ambient temperature	-10 to 55°C, storage: -25 to 75°C					
ment	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH					
rotect	on structure	IP20 (IEC standards)					
Protection circuit		Surge, Short-circuit, Overheating and static protection, Reversed polarity protection circuit					
Tolect	on circuit	Over current protection (Operated at min. 0.17A) Over current protection (Operated at min. 0.7A)					
Indicator		Network status (NS) LED (Green, Red), Module status (MS) LED (Green, Red) I/O status LED (Input: Green, Output: Red)					
Material		Front case: PC, Body case: PC					
Mounting		DIN Rail or Screw lock type					
Isolation type		I/O and inner circuit: insulated, Modbus and inner circuit: non-insulated, unit power: non-insulated					
Approv	al	C€					
Jnit	Basic unit	Approx. 66g					
weight	Expansion unit	Approx. 56g					

X Environment resistance is rated at no freezing or condensation.

Unit Descriptions

O Basic unit



1. Network connector

No.	For	Organization	
5	24VDC (+)	5: 24VDC	
4	GND	4: GND	
3	N·C	3: N·C	
2	В	•) 2: B	
1	А	[_•_] 1: A	

2. Rotary switch for node address

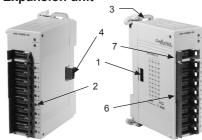
: Two rotary switches are used for setting address. X10 switch represents the 10's multiplier and X10 switch represents the 1's multiplier.

3. Status LED

- : It is LED for displaying Unit status (MS) and Network status (NS).
- 4. I/O status LED: It is LED for displaying I/O status.
- 5. Rail Lock: It is used for mounting DIN Rail or with screws.
- 6. Connnector output part: It is used for connecting an expansion unit.
- 7. Sensor connector: It is connector for connecting external device I/O.
- 8. External power connector: It is used for supplying external power.

Modbus Digital Remote I/O

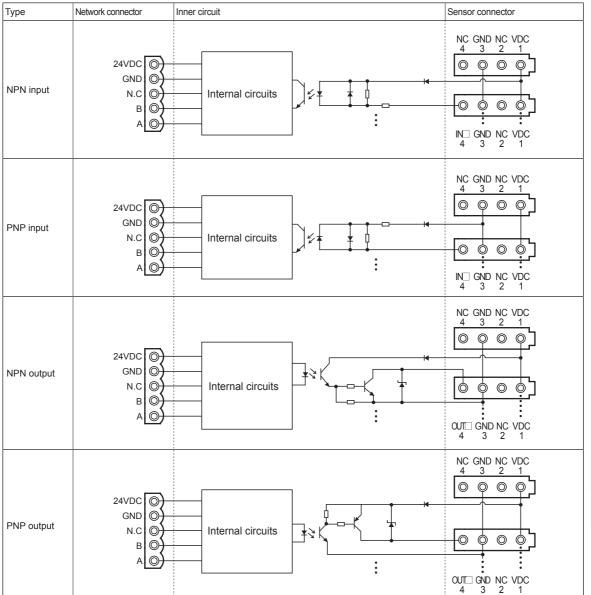
⊚ Expansion unit



1. Connnector input part

- :It connects an Expansion unit and is joined into the connnector output part.
- 2. I/O status LED: It is LED for displaying I/O status.
- 3. Rail Lock
- : It is used for mounting DIN Rail or with screws.
- 4. Connnector output part: It is used for connecting an expansion unit.
- **5. Sensor connector**: It is connector for connecting external device I/O.
- 6. External power connector: It is used for supplying external power.

■ I/O Circuit Diagram



※IN□ IN0 to IN7, OUT□ OUT0 to OUT7

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary

Rotary Encoders

(G)

(H)

Temperature Controllers

(I) SSRs / Power Controllers

...

(M) Tacho / Speed / Pulse

splay

O) Sensor

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

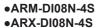
(R) Graphic/ Logic Panels

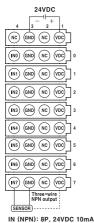
> S) ield letwork

(T) Software

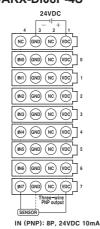
ARM Series

Connections





•ARM-DI08P-4S •ARX-DI08P-4S



•ARM-DO08N-4S •ARX-DO08N-4S

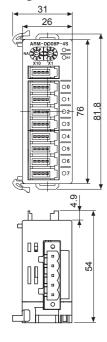


•ARM-DO08P-4S •ARX-DO08P-4S

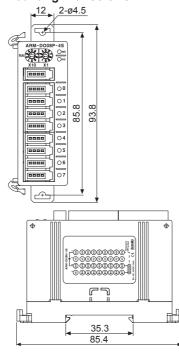


Dimensions

Mounting DIN rail



• Mounting with screws



(unit:mm)

X Same dimensions are applied to both basic and expansion unit.

Status LED

Status LED			(☆: On, ★: Flash, •: Off)	
lt	LED sta	atus	Description	
Item	Red	Green	Description	
Module Status (MS) LED	☆	•	Error of expansion units	
	∴	•	Error of MAC ID	
	•	☆	Normal operation	
	•	•	Power is not supplied	
Network Status (NS) LED	☆	•	Not supported communication speed (At auto baud rate)	
	∴	•	Error of packet	
	•	☆	Normal communication	
	•	∴	Communication standby	

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Modbus Digital Remote I/O

Setup And Installation

O Setting node address

- Setup address is by rotary switches or by inner EEPROM.
- If the rotary switches are "00", the address is set by inner EEPROM. The others, the desired number of rotary switches is that address.

By rotary switch for address

① Two rotary switches are used for setting address.

X10 switch represents the 10's multiplier and X10 switch represents the 1's multiplier.

Address is settable from 0 to 99.



The ×10 and ×1 switches point at '3', the node address is '33'.

X10 X1

②After setting the desired node address, re-supply the unit power for applying the changed address.

• By in the EEPROM for address

- During communicate status with master system (PLC or PL), set the desired address on the 41029 EEPROM MAC ID parameter.
- The set address is changed after unit power is supplied. Re-supply the unit power for applying the changed address.

O Unit Installation

Mounting on panel

- ① Pull two Rail locks on the rear part of a unit, there is a fixing screw hole.
- 2) Place unit on a panel to be mounted.
- ③ Make a hole on a fixing screw hole position.
- 4 Fasten the screw to fix the unit tightly. Please set the tightening torque under 0.5N m.

Mounting on DIN rail

- ①Pull two Rail locks on the rear part of a unit.
- @Place the unit on DIN rail to be mounted.
- ③Press Rail locks to fix the unit tightly.

• Connection of basic and expansion unit

- ① Turn OFF the power of a basic unit.
- 2 Remove the cover of connector for extension with nippers.
- ③ Connect connector input part of an expansion unit and connector output part of a basic unit with the connector which is enclosed with an expansion unit box.
- ④ Connected expansion units are installed as the right figure.
- Supply power to the basic unit.
 - (re-supply power to the basic unit, and it recognizes expansion units.)

Terminating Resistance

• 120 Ω • 1% of metallic film • 1/4W

**Connect terminating resistances on the both ends of the network cables. If not connecting terminating resistances, impedance can be too high or low. It may cause network problems.

■ Caution During Use

- Turn OFF the power before connecting or disconnecting expansion units.
- Addresses of connected units on network should not be duplicated. If you change an address with rotary switch or EEPROM during operation, unit status (MS) red LED flashes and it communicates with a previous node address.
 Re-supply power and the changed node address is applied.
- Communication speed which is set on upper system (PC, PLC, etc) is set automatically.
 If you change the communication speed during operation, network status (NS) red LED turns ON and it does not communicate. Re-supply power and it operates normally.
- Make sure to use standards communication cables.
 - It may cause communication error if non-standards cables are used.
- Make sure to examine disconnection or short-circuit before connecting cables.
- Avoid installing the units where severe dust exists or where corrosion may occur.
- This unit may be used in the following environments.
- Indoor
- Altitude: Under 2,000m
- Pollution degree 2
- · Installation category II

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