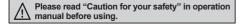
Small And Light, Common Type

Features

- Easy to mount at a narrow space with small size and light weight.
- Convenient to adjust the sensitivity by external sensitivity adjustment control. (Diffuse reflective type only)
- Easy to mount by screw type in mounting hole.
- Reverse power polarity protection circuit.







 \mathbb{X} MS-5, MST- \square is sold separately.

Specifications

oe stance	Through-beam	Determelie	
stance		Retroreflective	Diffuse reflective
	3m	0.1 to 1m ^{×1}	200mm ^{×2}
rget	Opaque materials of Min. Ø8mm	Opaque materials of Min. Ø60mm	Transparent, Translucent, Opaque materials
	_		Max. 10% at rated setting distance
time	Max. 3ms		
ply	12-24VDC ±10% (Ripple P-P: Max. 10%)		
nsumption	Max. 45mA Max. 40mA		
е	Infrared LED (940nm)		
adjustment	Fixed		Adjustable VR
node	Dark ON		Light ON (Dark ON: Option)
put	NPN open collector output •Load voltage: Max. 30VDC •Load current: Max. 100mA •Residual voltage: Max. 1V		00mA •Residual voltage: Max. 1V
circuit	Reverse polarity protection		
	Operation indicator: red LED		
esistance	Min. 20MΩ (at 500VDC megger)		
tance	±240V the square wave noise (pulse width: 1μs) by the noise simulator		
trength	1,000VAC 50/60Hz for 1minute		
	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for 2 hours		in.) in each X, Y, Z direction for 2 hours
	500m/s² (approx. 50G) in each X, Y, Z direction for 3 times		times
Ambient illumination	Sunlight: Max. 11,0001x Incandescent lamp: Max. 3,0001x (Receiver illumination)		
Ambient temperature	-10 to 60°C, storage: -25 to 70°C		
Ambient humidity	35 to 85%RH, storage: 35 to 85%RH		
	Case: ABS, Sensing part: PC Case: ABS, Sensing part: Acrylic		Acrylic
	Ø4mm, 3-wire, Length: 2m (Emitter of through-beam type: Ø4mm, 2-wire, Length: 2m) (AWG22, Core diameter: 0.08mm, Number of cores: 60, Insulator out diameter: Ø1.25mm)		
ndividual	_	Reflector (MS-2)	VR adjustment driver
Common	Mounting bracket, Bolts/nuts		
	C€		
i	Approx. 170g	Approx. 105g	Approx. 88g
	sumption e adjustment node but sircuit esistance tance trength ambient illumination ambient temperature ambient humidity	ime Max. 3ms 12-24VDC ±10% (Ripple for sumption) Max. 45mA Infrared LED (940nm) Adjustment Fixed Dark ON NPN open collector output Load voltage: Max. 30V Besistance Min. 20MΩ (at 500VDC modules) Fance ±240V the square wave not strength 1,000VAC 50/60Hz for 1md 1.5mm amplitude at frequents and in the sumption of the sumpt	me Max. 3ms 12-24VDC ±10% (Ripple P-P: Max. 10%) Issumption Max. 45mA Max. 40mA Infrared LED (940nm) Adjustment Fixed Dark ON NPN open collector output Load voltage: Max. 30VDC Load current: Max. 10 per sistance Min. 20MΩ (at 500VDC megger) Lance ±240V the square wave noise (pulse width: 1μs) by the square wave noise

^{※1:} It is mounting distance between sensor and reflector MS-2 and it is the same when MS-5 is used. It is detectable under 0.1m. When using reflective tapes, the reflectivity will vary by the size of the tape. Please refer to the "■Reflectivity By Reflective Tape Model" table before using the tapes.

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X2: It is for Non-glossy white paper (200×200mm)

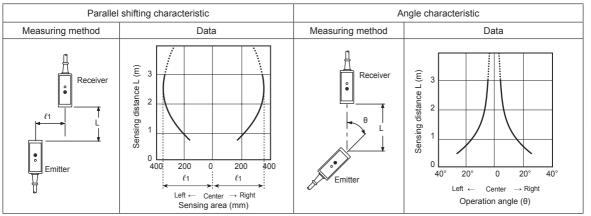
XThe temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Amplifier Built-in Type For General Purpose

■ Feature Data

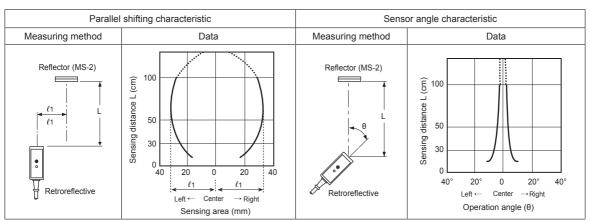
Through-beam type

BM3M-TDT



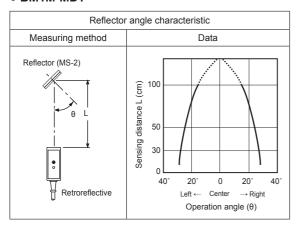
Retroreflective type

BM1M-MDT



Retroreflective type

BM1M-MDT



O Diffuse reflective type

BM200-DDT

Sensing area characteristic				
Measuring method	Data			
Standard sensing target: Non-glossy white paper 200×200mm	(Cm) 20 20 30 20 0 20 30 30 20 0 0 10 30 Sensing area (mm)			

(C) Door/Area Sensors

(D) Proximity Sensors

(F) Rotary Encoder

(I) SSRs / Power Controllers

(M) Tacho / Speed / Pulse Meters

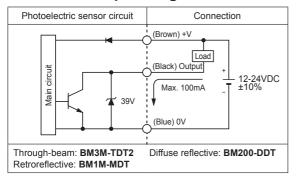
(O) Sensor Controllers

(P) Switching Mode Power Supplies (Q) Stepper Motors

(R) Graphic/ Logic Panels

A-45 **Autonics**

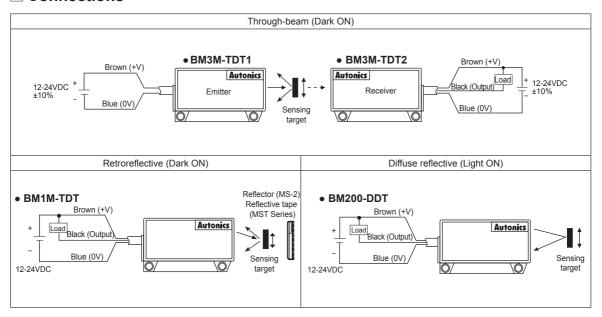
■ Control Output Diagram



Operation Mode

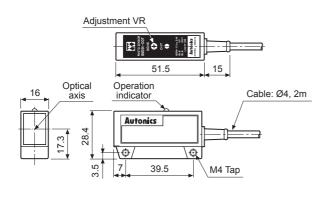
Operation mode		Light ON
Receiver operation	Received light	
Receiver operation	Interrupted light	
Operation indicator	ON	
(red LED)	OFF	
Transistar autaut	ON	
Transistor output	OFF	
Operation mode	Dark ON	
Desciver energtion	Received light	
Receiver operation	Interrupted light	
Operation indicator	ON	
(red LED)	OFF	
Transistor output	ON	
Transision output	l OFF	

Connections

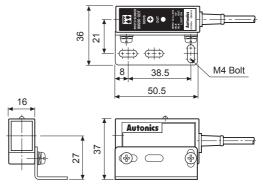


Dimensions

(unit: mm)



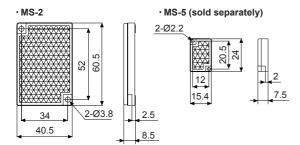
Connect the bracket



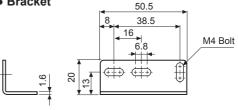
A-46 Autonics

Amplifier Built-in Type For General Purpose

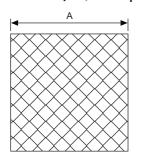
Reflector



Bracket



Reflective tape (sold separately)



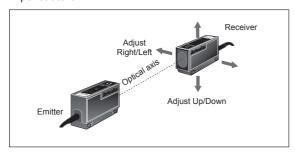


	(unit: mm)
	A
MST-50-10	□50
MST-100-5	□100
MST-200-2	□200

Mounting And Sensitivity Adjustment

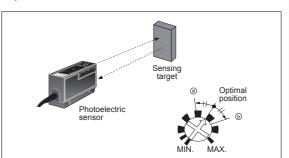
Through-beam type

- 1. Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other.
- 2. Set the receiver in center of position in the middle of the operation range of indicator by adjusting the receiver or the emitter right and left, up and down.
- 3. After the adjustment, check the stability of operation by putting the object at the optical axis.
- XIf the sensing target is translucent body or smaller than Ø8mm, it can be missed by sensor because light penetrate it.



O Diffuse reflective type

- 1. The sensitivity should be adjusted depending on a sensing target or mounting place.
- 2. Set the target at a position to be detected by the beam, then turn the adjustment VR until position @ where the operation indicator turns ON from min. position of the adjustment VR.
- 3. Take the target out of the sensing area, then turn the adjustment VR until position (6) where the operation indicator turns ON. If the indicator dose not turn ON, max. position is (b).
- 4. Set the adjustment VR at the center of two switching position @, b.



XThe sensing distance indicated on specification chart is for 200×200mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.

(C) Door/Area Sensors

(D) Proximity

(F) Rotary Encode

(I) SSRs / Power Controllers

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors

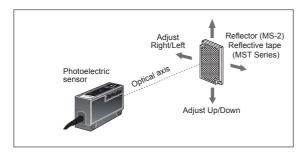
(R) Graphic/ Logic Panels

A-47 **Autonics**

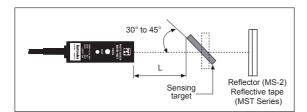
BM Series

Retroreflective type

- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector (MS-2) or reflective tape face to face.
- Set the photoelectric sensor in the position which indicator turns on, by adjusting the reflector, reflective tape or the sensor right and left, up and down.
- 3. Fix both units tightly after checking that the unit detects the target.
- If using more than 2 photoelectric sensors in parallel, the space among them should be more than 30cm.



※If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor. Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30° to 45° against optical axis.



- XIf the mounting place is too narrow, please use MS-5 instead of MS-2.



Reflectivity By Reflective Tape Model

MST-50-10 (50×50mm)	70%
MST-100-5 (100×100mm)	110%
MST-200-2 (200×200mm)	170%

- XThis reflectivity is based on the reflector (MS-2).
- ※Reflectivity may vary depending on usage environment and installation conditions.

The sensing distance and minimum sensing target size increase as the size of the tape increases.

Please check the reflectivity before using reflective tapes.

※For using reflective tape, installation distance should be min. 20mm.

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