DIN W48×H48mm, W72×H36mm, W72×H72mm Counter/Timer

Features

- Prescale value setting range 6-digit model: 0.00001 to 99999.9 / 4-digit model: 0.001 to 999.9
- Communication function supported (communication model): RS485 (Modbus RTU)
- One-shot output time setting range 0.01 sec. to 99.99 sec. by setting per 10ms
- •[Counter]

9 input modes/11 output modes

BATCH counter,

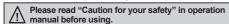
Count Start Point (counting initial value) setting function

•[Timer]

11 output modes

Various time setting range— 6-digit model: 0.001 sec. to 99999.9 hour / 4-digit model: 0.001 sec. to 9999 hour '0' time setting function

Selectable timer memory retention function for indicator model.





DAQMaster (Comprehensive Device Management Program)

• DAQMaster is comprehensive device management program for convenient management of parameters and multiple device data monitoring.

 Visit our website (www.autonics.com) to download user manual and comprehensive device management program.

Item	Minimum requirements
System	IBM PC compatible computer with Intel Pentium III or above
Operations	Microsoft Windows 98/NT/XP/Vista/7/8/10
Memory	256MB+
Hard disk	1GB+ of available hard disk space
VGA	Resolution: 1024×768 or higher
Others	RS-232 serial port (9-pin), USB port

< DAQMaster screen >

123456

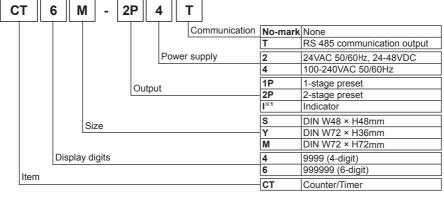
123458

3456

a: 423458



Ordering Information



X1: CT4S model does not support indicatior type.

Communication Specification

	-
Comm. protocol	Modbus RTU with 16-bit CRC
Connection type	RS485
Application standard	Compliance with EIA RS485
Max. connection	31 units (address: 1 to 127)
Synchronous method	Asynchronous
Comm. type	Two-wire half duplex
Comm. distance	Max. 800 m
Comm. speed	2400, 4800, 9600 (factory default), 19200, 38400bps
Comm. response time	5 to 99ms (factory default: 20ms)
Start bit	1-bit (fixed)
Data bit	8-bit (fixed)
Parity bit	None (factory default), Even, Odd
Stop bit	1, 2-bit (factory default: 2-bit)

XIt is recommended to use communication converter, RS485 to Serial converter (SCM-38I, sold separately), USB to RS485 converter (SCM-US48I, sold separately). Please use a proper twist pair for RS485 communication.

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(I) SSRs / Power Controllers

(N) Display Units

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

Specifications

Seri	es				CTS		CTY		СТМ	
		1-stag	ge pres	et	CT4S-1P□□	CT6S-1P□□	CT6Y-1P□□	-	CT6M-1P	
		2-stag	ge pres	et	CT4S-2P□□	CT6S-2P□□	CT6Y-2P□□		CT6M-2P□□	
		Indica	ator		<u> </u>	CT6S-I□□	CT6Y-I□□		СТ6М-І□□	
Display digits		4-digit	6-digit	6-digit		6-digit				
Display method			segment (counting value: red, setting value: yellow-green) LED method							
Char	acter	. (Countin	ig value	6.5×10mm					
	W×H		Setting		4.5×8mm	3.5×7mm	3.5×7mm		5×9mm	
			AC volt	_	+	00-240VAC 50/60Hz				
Pow	er sup	onlv ⊦		voltage	24VAC 50/60Hz					
Dorn	aiooib		age ran		90 to 110% of ra					
			AC volt	<u> </u>	Max. 12VA	aleu vollage				
Powe	er sumpti					DO: M=:: 0\M				
				voltage	AC: Max. 10VA,	, DC. Max. ow				
		INA/IN		speed	Selectable 1cps	s/30cps/1kcps/5kd	:ps/10kcps			
			ng rang	<u> </u>	-999 to 9999	-99999 to 99999	00			
Cour	nter	Counti	ng rang	je		-99999 10 99998	19			
		Scale			Decimal point up to third digit	Decimal point up	to fifth digit			
	ł	Min ei	gnal wi	dth	<u> </u>	_l Selectable 1ms/20)ms			
		wiii 1. 31	grial WI		+		9999s. 99m59.99s	999m50 0c 00	199m59s 00000 0	m 999000m
		Time r	ange		,	.998, 99999.98, 99 99h59m, 99999.9h	,	, פפ.פטווופפס, 99	, , , , , , , , , , , , , , , , , , ,	ııı, ฮฮฮฮฮฮIII,
	ŀ	Operat	tion me	thod		t down, Count Up/				
	ł	Орста	tion inc	tilou	Count up, Coun	t down, oddin op/	DOWN		INA, RESET, IN	ILIDIT DATCI
		Min si	gnal wi	dth	INA INH RESE	ET signal: Selecta	hle 1ms/20ms		RESET signal:	NITIDIT, DATC
Time	er		griai W	ou i	110,1,1111,11202	_ r oignai. ooloota	510 11110/201110		Selectable 1ms	:/20ms
	Ì	Repea	t error							
					In case of nowe	r ON start: May 4	.0.01% ±0.05c			
		Set error		In case of power ON start: Max. ±0.01% ±0.05s In case of signal start: Max. ±0.01% ±0.03s						
		Voltag	e error		In case of signa	I start: Max. ±0.01	1% ±0.03s			
			e error		In case of signa	ll start: Max. ±0.01	1% ±0.03s			
		Voltage Temp.								
	-	Temp.			Selectable volta	age input or no-vo	Itage input	OC. [L1: 0-2VDC		
Inpu		Temp.			Selectable volta [Voltage input]-i	age input or no-vo	ltage input 5.4kΩ, [H]: 5-30VI			Max. 2VDC
	t meth	Temp.	error		Selectable volta [Voltage input]-i [No-voltage input]	age input or no-vo input impedance: ut]-short-circuit im	Itage input			Max. 2VDC
	t meth	Temp.	error		Selectable volta [Voltage input]-i [No-voltage input]-0.01s to 99.99s	age input or no-voinput impedance: ut]-short-circuit im setting	ltage input 5.4kΩ, [H]: 5-30VI pedance: Max. 1k	Ω, short-circuit	residual voltage: I	
	t meth	Temp.	error	1 stage	Selectable volta [Voltage input]- [No-voltage input] 0.01s to 99.99s Standard	age input or no-vo input impedance: ut]-short-circuit im	ltage input 5.4kΩ, [H]: 5-30VI pedance: Max. 1k Standard		residual voltage: I	Max. 2VDC
One-	t meth	Temp.	time	1-stage	Selectable volta [Voltage input]-i [No-voltage input]-0.01s to 99.99s	age input or no-voinput impedance: ut]-short-circuit im setting	Itage input 5.4kΩ, [H]: 5-30VI pedance: Max. 1k Standard SPDT(1c): 1	Ω, short-circuit	residual voltage: I	
One-	t meth	Temp. nod output	error	1-stage 2-stage	Selectable volta [Voltage input]- [No-voltage input] 0.01s to 99.99s Standard	age input or no-voinput impedance: ut]-short-circuit im setting	itage input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1,	Ω, short-circuit	residual voltage: I	Comm.
One-	t meth	Temp. nod output	time Type	2-stage	Selectable volta [Voltage input]- [No-voltage input]- 0.01s to 99.99s Standard SPDT(1c): 1	age input or no-voinput impedance: ut]-short-circuit imsettingComm.	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1	Ω, short-circuit Comm. SPST(1a): 2	Standard SPDT(1c): 1 SPST(1a): 1, SF	Comm.
One-	shot Conta	Temp. nod output act	time	2-stage	Selectable volta [Voltage input]- [No-voltage input]- 0.01s to 99.99s Standard SPDT(1c): 1	age input or no-voinput impedance: ut]-short-circuit imsettingComm.	itage input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1,	Comm. SPST(1a): 2 sistive load	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res	Comm.
Control output	t meth-shot Conta	Temp. hod output act t	time Type	2-stage ity 1-stage	Selectable volta [Voltage input]- [No-voltage input]- 0.01s to 99.99s Standard SPDT(1c): 1	age input or no-voinput impedance: ut]-short-circuit imsettingComm.	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1	Ω, short-circuit Comm. SPST(1a): 2	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res	Comm.
Control output	t meth-shot Contacutpu Solid outpu (NPN	Temp. hod output act tt state toppen	time Type Capac	2-stage ity 1-stage 2-stage	Selectable volta [Voltage input]- [No-voltage input]- 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC 5A resi	age input or no-voinput impedance: ut]-short-circuit imsetting Comm.	Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res	Comm. SPST(1a): 2 sistive load	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res	Comm. PDT(1c): 1 istive load
Control output	contact solid output (NPN collect	Temp. nod output act tt state toppen ctor)	time Type Capac Type Capac	2-stage ity 1-stage 2-stage	Selectable volta [Voltage input]-[No-voltage input]-[No-voltage input]-10.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC 5A residual Max. 30VDC, 10	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. comm. comm.	Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res	Comm. SPST(1a): 2 sistive load	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res	Comm. PDT(1c): 1 istive load
Control output	contact Solid output (NPN collect rnal p	Temp. nod output act tt state t open ctor) oower s	time Type Capac Type Capac Supply	2-stage ity 1-stage 2-stage	Selectable volta [Voltage input]-[No-voltage input]- [No-voltage input]- 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC 5A resident Max. 30VDC, 10 Max. 12VDC ±1	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA	Itage input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res	Comm. SPST(1a): 2 sistive load	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res	Comm. PDT(1c): 1 istive load
Control output Exte	Conta Conta Solid outpu (NPN collec	Temp. nod output act it state it open ctor) oower setentio	time Type Capac Type Capac supply	2-stage ity 1-stage 2-stage	Selectable volta [Voltage input]- [No-voltage input]- [No-voltage input]- 0.01s to 99.99s Standard SPDT(1c): 1 SPST(1a): 2 250VAC 5A resi Max. 30VDC, 10 Max. 12VDC ±1 Approx. 10 year	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load 00mA 0%, 100mA cs (non-volatile me	standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A resembly	Comm. SPST(1a): 2 sistive load	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res	Comm. PDT(1c): 1 istive load
One- Control output Exte Mem	Conta Conta Solid outpu (NPN collections) rnal proof re-	Temp. nod output act tt state tt open ctor) oower setentio resista	time Type Capac Type Capac supply n	2-stage ity 1-stage 2-stage	Selectable volta [Voltage input]-[No-voltage input]-[No-voltage input]-[No-voltage input]-(No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA rs (non-volatile ment 500VDC megge	standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A resembly	Comm. SPST(1a): 2 sistive load	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res	Comm. PDT(1c): 1 istive load
One- Control ontbut Exte Mem	Conta Conta Solid outpu (NPN oory real p pory real lation	Temp. nod output act tt state tt open ctor) ower setentio resista streng	time Type Capac Type Capac Supply n ance	2-stage ity 1-stage 2-stage	Selectable volta [Voltage input]-[No-voltage input]-[No-voltage input]-[No-voltage input]-(No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min.	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 —	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res	Comm. PDT(1c): 1 istive load
One- Control ontbut Exte Mem	Conta Conta Solid outpu (NPN oory real p pory real lation	Temp. nod output act tt state t open ctor) oower setentio resista streng istance	time Type Capac Type Capac Supply n ance	2-stage ity 1-stage 2-stage ity	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min. bise by noise simu.	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 emory) r)	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load
One- Courton onthort Exte Mem Insul Diele Nois	-shot Contactoric	Temp. nod output act tt state t open ctor) oower setentio resista streng istance	time Type Capac Type Capac Supply n ance	2-stage ity 1-stage 2-stage ity	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min. bise by noise simu.	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load
One- One- Courtor onthor Exte Mem Insul Diele Nois	Conta Conta Solid outpu (NPN oory real p pory real lation	Temp. nod output act tt state topen ctor) oower setentio resista streng istance	time Type Capac Type Capac Supply n ance	2-stage ity 1-stage 2-stage ity	Selectable volta [Voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- Selectable voltage in	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min. bise by noise simulate at frequency of	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 emory) r)	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X,	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
One- One- Exte Mem Insul Diele Nois	contact to metric to metri	Temp. nod output act tt state topen ctor) oower setentio resista streng istance	time Type Capac Type Capac Supply n ance th	2-stage ity 1-stage 2-stage ity	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min. bise by noise simulate at frequency of	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 emory) r) silator (pulse width f 10 to 55Hz (for 1	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, nin.) in each X,	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
One- One- Exte Mem Insul Diele Nois	contact to metric to metri	Temp. nod output act tt state topen ctor) oower setentio resista streng istance	time Type Capac Type Capac Supply n ance th s Mechar Malfund	2-stage ity 1-stage 2-stage ity ity contact the stage of	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 semory) r) silator (pulse width f 10 to 55Hz (for 1 res)	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, nin.) in each X, 3 times	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
One- Induntion of the control of the	contact to metric should be should b	Temp. nod output act it state to open ctor) ower setentio resista streng istance	time Type Capac Type Capac Supply n ance th e Mechar Malfund Mechar	2-stage ity 1-stage 2-stage ity city city city city city city city	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 semory) r) silator (pulse width f 10 to 55Hz (for 1 r Y, Z direction for 3	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, nin.) in each X, 3 times	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
One- Induntion of the control of the	contact to metric to metri	Temp. nod output act tt state topen ctor) oower setentio resista streng istance	time Type Capac Type Capac Supply n ance th s Mechar Malfund Mechar Malfund Mechar	2-stage ity 1-stage 2-stage ity city city 1-stage 2-stage ity	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 semory) r) silator (pulse width f 10 to 55Hz (for 1 r Y, Z direction for 3	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, nin.) in each X, 3 times	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
One- Induction on the state of	Contact Solid Co	Temp. nod output act tt state topen ctor) oower setentio resista streng istance	time Type Capac Type Capac Supply n ance th e Mechar Malfund Mechar Malfund Mechar Malfund Mechar	2-stage ity 1-stage 2-stage ity city city 1-stage 2-stage ity	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min. bise by noise simulate at frequency of eat frequency of x. 30G) in each X, x. 10G) in each X, to operations	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 semory) r) silator (pulse width f 10 to 55Hz (for 1 r Y, Z direction for 3	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, nin.) in each X, 3 times	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
One- Induction on the state of	Contact Solid Co	Temp. nod output act tt state topen ctor) oower setentio resista streng istance cycle	time Type Capac Type Capac Supply n ance th e Mechar Malfund Mechar Malfund Mechar Malfund Mechar Malfund Mechar	2-stage ity 1-stage 2-stage ity ity 1-stage 2-stage ity ction ical ction ical ction ical ction	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min. bise by noise simulate at frequency of ext frequency of x. 30G) in each X, x. 10G) in each X, to operations perations perations perations perations	stange input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 semory) r) silator (pulse width f 10 to 55Hz (for 1 r Y, Z direction for 3	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, nin.) in each X, 3 times	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
One- tridino lo tridin	Contact Solid Co	Temp. Temp. Tomod output act tt state topen ctor) oower setentio resista streng istance cycle in struct	time Type Capac Type Capac Supply n ance th e Mechar Malfund Mechar Malfund Mechar Malfund Mechar Malfund Mechar Malfund Mechar Malfund Mechar	2-stage ity 1-stage 2-stage ity ity 1-stage 2-stage ity ity itial	Selectable volta [Voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- Sepson standard SPDT(1c): 1 SPST(1a): 2 250VAC 5A resitation Max. 30VDC, 10 Max. 12VDC ±1 Approx. 10 year Over. 100MΩ (a 2,000VAC 50/60 Square-wave notes of the sepson standard input)- Square-wave notes of the sepson standard input Square-wave notes of the sepson standard input)- Square-wave notes of the sepson standard input Square-wave notes of the sepson standard inp	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load	Itage input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 emory) r) Italator (pulse width f 10 to 55Hz (for 1 10 to 55Hz (for 1 Y, Z direction for 3 Y, Z direction for 3	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, nin.) in each X, 3 times	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
Diele Nois Shoo	Contactorion Solid doubter Solid doubter Solid doubter Solid doubter Solid Contact Solid S	Temp. Temp. Tomod output act tt state topen ctor) oower setentio resista streng istance cycle in struct	time Type Capac Type Capac Supply n ance th e Mechar Malfund Mechar Malfund Mechar Malfund Mechar Malfund Mechar	2-stage ity 1-stage 2-stage ity ity 1-stage 2-stage ity ity itial	Selectable volta [Voltage input]-[No-voltage input	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min. bise by noise simulate at frequency of ext frequency of x. 30G) in each X, x. 10G) in each X, to operations perations perations perations perations	Itage input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 emory) r) Italator (pulse width f 10 to 55Hz (for 1 10 to 55Hz (for 1 Y, Z direction for 3 Y, Z direction for 3	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, nin.) in each X, 3 times	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 iistive load 2
Diele Nois Shoo	Contact Solid Co	Temp. Temp. Tomod output act tt state topen ctor) oower setentio resista streng istance cycle in struct	time Type Capac Type Capac Supply n ance th e Mechar Malfund Mechar Malfund Mechar Malfund Mechar Malfund Mechar Malfund Mechar Malfund Mechar	2-stage ity 1-stage 2-stage ity ity 1-stage 2-stage ity ity itial	Selectable volta [Voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- [No-voltage input]- Sepson standard SPDT(1c): 1 SPST(1a): 2 250VAC 5A resitation Max. 30VDC, 10 Max. 12VDC ±1 Approx. 10 year Over. 100MΩ (a 2,000VAC 50/60 Square-wave notes of the sepson standard input)- Square-wave notes of the sepson standard input Square-wave notes of the sepson standard input)- Square-wave notes of the sepson standard input Square-wave notes of the sepson standard inp	age input or no-voinput impedance: ut]-short-circuit imsetting Comm. istive load —— 00mA 0%, 100mA rs (non-volatile ment 500VDC megge 0Hz for 1 min. bise by noise simulate at frequency of ext. 10G) in each X, x. 10G) in each X, to operations perations utes the standards of the	Itage input 5.4kΩ, [H]: 5-30VI spedance: Max. 1k Standard SPDT(1c): 1 SPST(1a): 1, SPDT(1c): 1 250VAC 3A res 1 emory) r) Italator (pulse width f 10 to 55Hz (for 1 10 to 55Hz (for 1 Y, Z direction for 3 Y, Z direction for 3	Ω, short-circuit Comm. SPST(1a): 2 sistive load 1 1μs) ±2kV min.) in each X, inin.) in each X, it imes it imes	Standard SPDT(1c): 1 SPST(1a): 1, SF 250VAC 5A res 2 3	Comm. PDT(1c): 1 istive load 2 1 hour 10 minutes

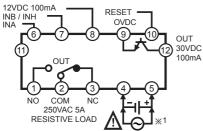
X1: The weight includes packaging. The weight in parentheses is for unit only.
X Environment resistance is rated at no freezing or condensation.

CT Series

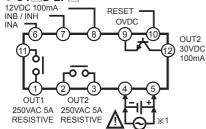
Connections

O CTS Series

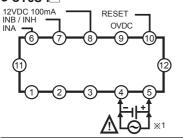
● CT S-1P



● CT S-2P

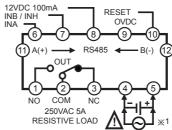


● CT6S-I

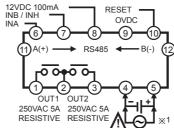


Be sure that connection is varied by supporting RS485 communication.

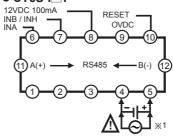
● CT S-1P T



● CT S-2P T

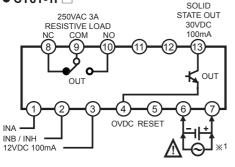


● CT6S-I□T

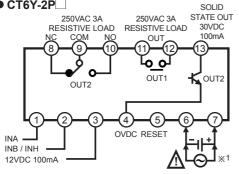


CTY Series

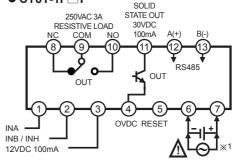
● CT6Y-1P



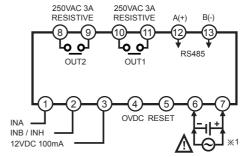
● CT6Y-2P

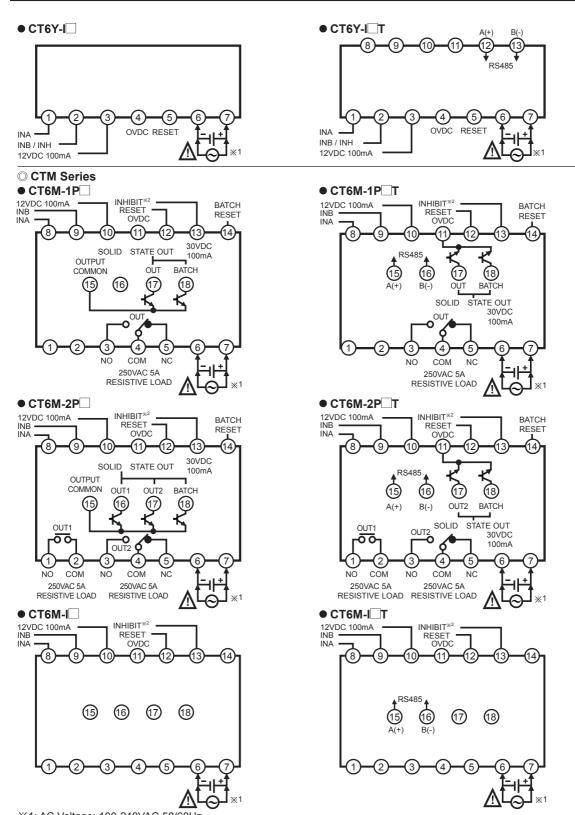


● CT6Y-1P



● CT6Y-2P□T





(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

Sensors

(F) Rotary Encoders

Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

(K)

(L)

(M) Tacho /

(N) Display Units

(O)

Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

Field Network Devices

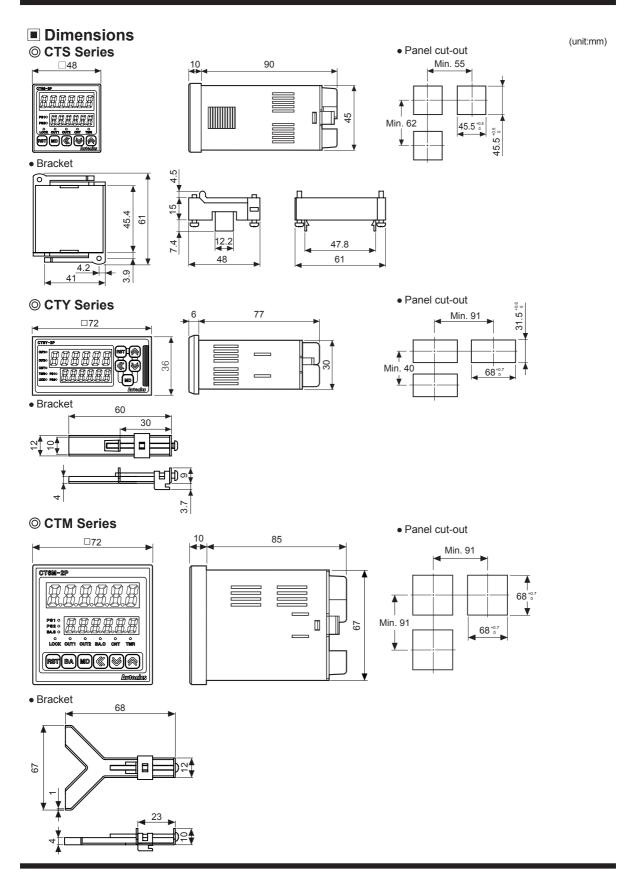
>) oftware

J-11

X1: AC Voltage: 100-240VAC 50/60Hz

AC/DC Voltage: 24-48VDC, 24VAC 50/60Hz

※2: Counter operation: If INHIBIT signal is applied, count input will be prohibited. Timer operation: If INHIBIT signal is applied, time progressing will stop. (HOLD)



J-12 Autonics

Sold Separately

© Communication converter

• SCM-38I (RS232C to RS485 converter) (€ [©



• SCM-US48I (USB to RS485 converter) C€ ☑



O Display Units (DS/DA-T Series)

DS/DA-T Series
 (RS485 communication input type display unit) CE









DS16-UT DS22/DA22-UT

DS40/DA40-_T DS60/DA60-_T

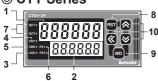
※Connect RS485 communication input type display unit (DS/DA-T Series) and RS485 communication output model of CT Series, the display unit displays present value of the device without PC/PLC.

Unit Description

CTS Series



© CTY Series



CTM Series



Model	Changed	Notice	
CT4S-1P			
CT6S-1P	PS2→PS	There are no	
CT6Y-1P	OUT2→OUT	PS1, OUT1 LEDs.	
CT6M-1P			
CT6S-I		There are no	
CT6Y-I	PS2→PS	PS1, OUT1,	
CT6M-I		OUT2 LEDs.	

XThe indicator type does not exist in CT4S model.

1. Counting value display component (red)

RUN mode: Displays counting value for counter operation or time progress value for timer operation.

Function setting mode: Displays setting item.

2. Setting value display component (yellow-green)

RUN mode: Displays setting value.

Function setting mode: Displays setting content.

- 3. Key lock indicator (LOCK): Turns ON for key lock setting.
- 4. Counter indicator (CNT): Turns ON for counter operation.
- **5. Timer indicator (TMR):** Flashes (progressing time) or Turns ON (stoping time) for timer operation.

6. Preset value checking and changing indicator (PS1, PS2):

Turns ON when checking and changing preset value.

- 7. Output indicator (OUT1, OUT2): Turns ON for the dedicated control output ON.
- 8. RST key

RUN mode: Press the RST key to reset the counting value.

BATCH counter mode: Press the RST key to reset the batch counting value.

9. MD key

RUN mode: Hold the MD key over 3 sec. to enter function setting mode(parameter setting).

Hold the MD key over 5 sec. to enter function setting mode(communication setting).

Function setting mode: Press the MD key to select function setting mode parameter.

Hold the MD key over 3 sec. to return RUN mode.

10. **≪**, **⋈**, **⋒ key**

1) 🗷 key

RUN mode: Press the key to enter preset mode.

Preset mode: Press the key to move preset digits.

2) ⊌, key

RUN mode: Hold the key over 1 sec. to enter Function setting check mode.

Preset mode: Used for increasing or decreasing preset value.

Function setting mode: Changes the settings.

Function setting check mode: Press the ${\Bbb S}$ key to move the previous parameter. Press the ${\Bbb S}$ key to the next parameter.

11. BA key

RUN mode: Press the RST key to enter BATCH counter indication mode.

12. BATCH output indicator (BA.O) (red)

13. BATCH preset value checking and changing indicator (BA.S) (yellow-green):

Turns ON when checking and changing BATCH preset value.

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors (E) Pressure Sensors

Sensors

(F) Rotary Encoders

Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

Timer:

Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field

Jevices

Γ) oftware

Input Connections

Brown

Black ×1

Blue

Sensor

• Solid-state input (Standard sensor: NPN output type sensor)

Inner circuit

of input part

Counter/Timer

CT Series

5.40

Counter/Timer CT Series Counter/Timer Sensor CT Series Brown +12\/ +12V 5 40 540 Black X1 **※2** Inner circuit Inner circuit of input part of input part ıδ Blue 0V 0V

X1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

X2: Counting speed: 1 or 30cps setting (Counter)

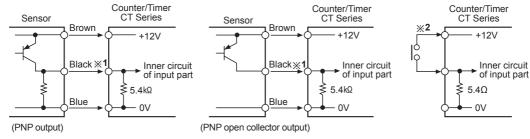
○ Voltage input (PNP)

(NPN output)

• Solid-state input (Standard sensor: PNP output type sensor)

Contact input

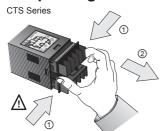
Contact input



(NPN open collector output)

- X1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part
- X2: Counting speed: 1 or 30cps setting (Counter)

■ Input Logic Selection[No-Voltage Input (NPN)/Voltage Input (PNP)]



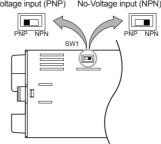
- 1. The power must be cut off.
- 2. Squeeze toward ① and pull toward ② as the figure. (CTS/CTY Series)
- 3. Select input logic by using input logic switch (SW1) inside Counter/Timer.
- 4. Push a case in the opposite direction of ②.
- 5. Then supply the power to counter/timer.
- Case detachment
 Squeeze toward ① a

Squeeze toward ① and pull toward ② as shown in picture.

↑ Turn OFF the power before changing input logic (PNP/NPN)

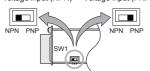
CTM

Voltage input (PNP) No-Voltage input (NPN)



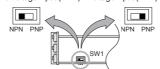


No-voltage input (NPN) Voltage input (PNP)



CTY

No-voltage input (NPN) Voltage input (PNP)



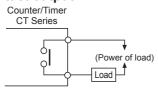
Error Display

Error display	Errors	Output status	How to return
PS10 FRI L	Failed in data loading for exsiting setting values	OFF	Power on again

J-14 Autonics

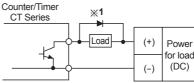
Output Connections

© Contact output



XUse proper load not to exceed the capacity.

O Solid-state output

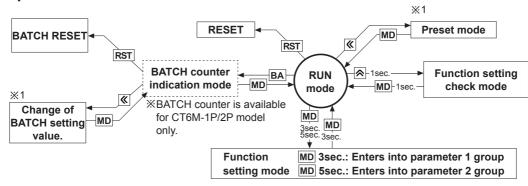


**Use proper load and power for load not to excess ON/OFF capacity (30VDC Max. 100mA Max.) of solid state output.

※Be sure not to apply reverse polarity of power.

X1: When using inductive load (Relay etc.), surge absorber (Diode, varistor etc.) must be connected between both sides of the load.

Operations And Functions



○ Change of preset (Counter/Timer)

• Even if changing the preset value, input operation and output control will continue. In addition, the preset value could be set to 0 and the output of 0 preset value turns ON. According to output mode, preset value could not be set to 0. (When setting to 0, preset value "0" will flash 3 times.)



In RUN mode, press the key to enter preset mode. 'PS1' indicator turns ON and first digit of preset value flashes.



Press the , and keys to set the desired value (example, IBU). Press the MD key to enter the PS2 setting mode.



Press the <a> √, <a> △ and <a> ✓ keys to set the desired value (example, <a> □ □). Press the <a> MD key to return RUN mode.

O Function setting check mode

Setting value of function setting mode can be confirmed using the ⋈ and ⋈ keys.

Switching display function in preset indicator

Setting value 1(PS1) and setting value 2(PS2) are displayed each time pressing MD key in dual preset model. (In timer, it is available for pnd, pnd, or pnd, output mode.)

Reset

In RUN mode or function setting mode, if pressing RST key or applying the signal to the RESET terminal on the back side, present value will be reset and output will maintain off status. When selecting voltage input (PNP), short no. 10 and no. 12 terminals, or when selecting no-voltage input (NPN), short no.11 and no.12 terminals to reset.

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G)

(H) Temperature

(I) SSRs / Power Controllers

Controllers

504111010

(M) Tacho / Speed / Pulse Meters

Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

■ BATCH Counter (For CT6M-1P□ □ /CT6M-2P□ □ Model Only)

In BATCH counter indication mode, 'BATCH counter value' is displayed in count indicator and 'BATCH counter setting value' is displayed in preset indicator.

O Change of BATCH setting value

If pressing BA key in Run mode, it will enter into BATCH counter indication mode.

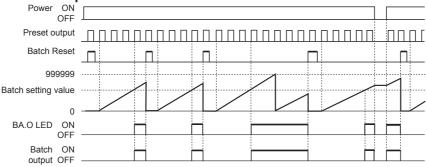


It enters into settingvalue change mode using <a> key. (BA.S lights, first digit of setting value flashes.)



BATCH value is set to '200' using , and wkeys, then press MD key to complete BATCH setting value and move to BATCH counter indication mode.

© BATCH counter operation



BATCH counting operation

- BATCH counting value is increasing until BATCH reset signal applied. BATCH counting value will be circulated when it is over 999999.

 1) BATCH counting operation in Counter: Counts the number of reaching setting value of CT6M-1P or reaching dual setting value of CT6M-2P
 - 2) BATCH counting operation in Timer: Counts the number of reaching setting time. (In case of "F L L" output mode, count the number of reaching T.off setting time and T.on setting time.)

◎ BATCH output

- If input signal is applied while changing BATCH setting value, counting operation and output control will be performed.
- If BATCH count value equals to BATCH setting value, BATCH output will be ON and maintain ON status until BATCH reset signal is applied.
- When the power is cut off then resupplied in status of BATCH output is ON, BATCH output maintains ON status until BATCH reset signal is applied.

BATCH reset input

- If pressing RST key or applying the signal to BATCH reset terminal on the back side panel, BATCH counting value will be reset. When selecting voltage input (PNP), short terminals 10 and 14, or when selecting no-voltage input (NPN), short terminals 11 and 14 to reset.
- When BATCH reset is applied, BATCH counting value maintains at 0 and BATCH output maintains in the OFF status.

Application of BATCH counter function

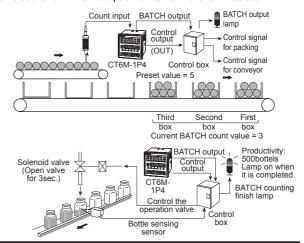
Counter

In case, put 5 products in a box then pack the boxes when they reaches to 200.

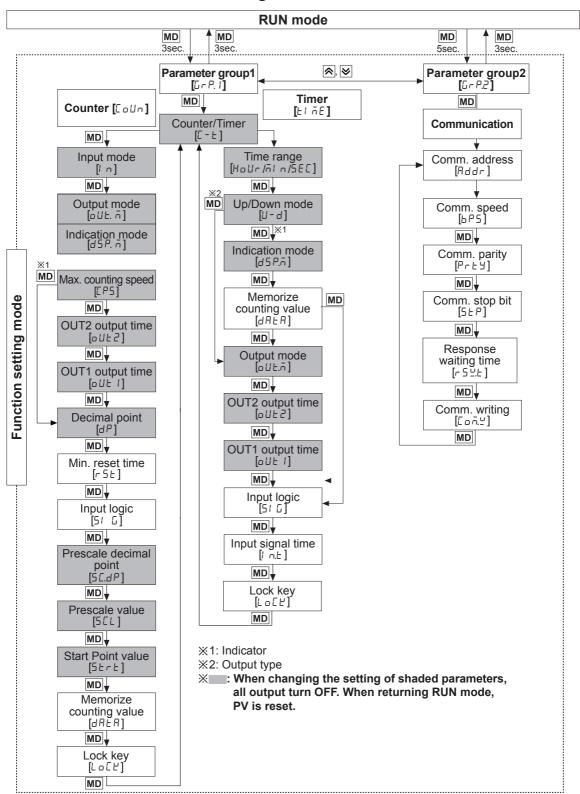
Counter preset setting value="5", BATCH setting value="200"
 When the count value of counter reaches to the preset value "5", the control output (OUT) will be on, and at this time the count value of the BATCH counter will be increased by "1". The control box which is received the control output (OUT) repeatedly controls conveyor to move the full box and to place the next empty box for standby. When the BATCH count value reaches to "200", BATCH output will be ON. Then the control box stops conveyor and provides a control signal for packing.

Timer

Fills milk into the bottle for 3sec. (setting time) When 500 bottles are filled, BATCH counting finish lamp is turned on. (Setting time: 3sec., BATCH setting value: 500)



■ Flow Chart For Function Setting Mode



XIf changing Parameter group1 setting value, display value and output are reset.

XParameter 2 group is not available to non-communication models.

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Sockets

(I) SSRs / Power Controllers

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

J-17

■ Parameter Setting (Counter)

(MD key: Moves the settings, ⋈, key: Changes the settings)

Parameter	Setting
Counter/ Timer [[- +]	EaUn ← ► El ñE
Input mode	Ud-[←→UP←→UP-1←→UP-2←→dn←→dn-1←→dn-2←→Ud-R←→Ud-b ♠
Output mode	• Input mode is UP, UP-1, UP-2 or dn, dn-1, dn-2, F ← → n ← → □ ← → □ ← → □ ← → □ ← → □ • Input mode is UP, UP-1, UP-2 or dn, dn-1, dn-2, F ← → n ← → □
	• Input mode is Ud-A, Ud-b, Ud-E, F ← ► □ ← ► □ ← ► □ ← ► □ ← ► □ ← ► □ ← ► □ ← ► □ ← □ ←
	XIf max. counting speed is 5kcps, and output mode is d, max. counting speed is automatically changed as 30cps, factory default.
Indication mode [d5P.ā]	■ In case of the indicator type ※In case of the indicator type, indicate mode selection [d5Pā] is displayed. ###################################
Max. counting speed	 **Max. counting speed is when duty ratio of INA or ∃□ → Iピ → 5ピ → I□ ピ → I INB input signal is 1:1. It is applied for INA, or INB input as same. **When output mode is d, set max. counting speed one among 1cps, 30cps, or 1kcps.
OUT2 output time ^{×1} [oUt 2]	XSet one-shot output time of OUT2. XSetting range: 00.01 to 99.99sec. XWhen input mode is F, n, 5, E, d, □ □ □ E does not appear. (fixed as HOLD)
OUT1 output time*1 [alle 1] OUT	XSet one-shot output time of OUT1. XSetting range: 00.01 to 99.99sec., Hold. XWhen 1st digit is flashing, press the key once and H□L d appears. XWhen input mode is 5, E, d, □UE I does not appear. (fixed as HOLD)
output time*1	XSetting range: 00.01 to 99.99sec. XWhen input mode is F, □, 5, E, d, □ UE.E does not appear. (fixed as HOLD)
Decimal point**2	• 4-digit type • 4-digit type • X Decimal point is applied to counting value and setting value.
Min. reset time [-5]	/ ← → ≥ □ , unit: ms
Input logic	nPn: No-voltage input, PnP: Voltage input **Check input logic value (PNP, NPN).
Prescale decimal point ^{×2}	• 6-digit type
[5 C.d P]	**Decimal point of prescale should not set smaller than decimal point [dP].
Prescale value [5 [L]	XSetting range of prescale value 6-digit type: 0.00001 to 99999.9, 4-digit type: 0.001 to 999.9
Start point value	 XSetting range (linked with decimal point [dP]): 6-digit type: 0.00001 to 999999, 4-digit type: 0.001 to 9999 XWhen input mode is dn, dn - 1, dn - 2, start point value does not appear.
Memory protection	※ELr: Resets the counting value when power OFF. ELr ←→ rEE ref: Maintains the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) ※ELr: Resets the counting value when power OFF. (memory protection) **The counting value when power OFF. **The counting value when power OFF. **The counting value when power OFF. (memory protection) **The counting value when power OFF. **Th
Key lock	L_DFF L_DE.I

X1: For 1-stage preset model, aUE I does not appear. The output time of aUE2 is displayed as aUEE.

^{※2:} Decimal point and prescale decimal point

⁻ Decimal point: Set the decimal point for display value regardless of prescale value.

⁻ Prescale decimal point: Set the decimal point for prescale value of counting value regardless of decimal point of display value.

■ Input Operation Mode (Counter)

Input mode	Counting chart	Operation
UP [UP]	INA H INB H No counting No counting A A A A A A A A A A A A A	
UP-1 [UP-1]	INA H INB H No counting 4 5	
UP-2 [uP-2]	INA H INB H No counting 3 4 Count 0	 ※When INA input signal is falling (→
Down [dn]	INA H No counting INB H No counting n-2 n-3 n-4 n-5 n-6 n-7	
Down-1 [dn - 1]	INA H INB H No counting O No counting O No counting	※When INA input signal is rising (it counts. ※INA: Counting input ※INB: No counting input
Down-2 [dn - 2]	INA H INB H No counting O	
Up/ Down-A [Ud - A]	INA H INB H Count 0 1 2 3 4 3 2 2 3 4	XINA: Counting input INB: Counting command input When INB is "L", counting command is up. When INB is "H", it is counting command is down.

(A)
Photoelectric
Sensors

(B)
Fiber
Optic
Sensors

(C)
Door/Area
Sensors

(D)
Proximity
Sensors

(E)
Pressure
Sensors

(F)
Rotary
Encoders

(G)
(G)
Temperature
Controllers

J) Counters

Timers

(M) Tacho / Speed / Pulse Meters

>) splay nits

onsor ontrollers

(P) Switching Mode Power Supplies

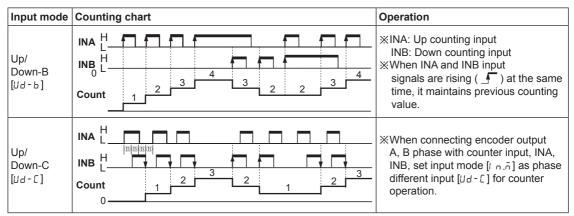
(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

> T) ioftware

■ Input Operation Mode (Counter)

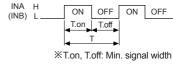


- X1: For selectable no-voltage input (PNP), voltage input (NPN) model.
- «A: over min. signal width, B: over than 1/2 of min. signal width. If the signal is smaller than these width, it may cause counting error (±1).
- XThe meaning of "H", "L"

Input method	Voltage input	No-voltage input	
Character	(PNP)	(NPN)	
Н	5-30VDC	Short	
L	0-2VDC	Open	

XMin. signal width by counting speed

Counting speed	Min. signal width
	Signal width
1cps	500ms
30cps	16.7ms
1kcps	0.5ms
5kcps	0.1ms
10kcps	0.05ms

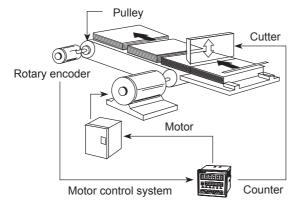


1cps=1Hz

Prescale Function (Counter)

This function is to set and display calculated unit for actual length, liquid, position, etc. It is called "prescale value" for measured length, liquid, or position, etc per 1 pulse. For example, when moving L, the desired length to be measured, and P, the number of pulses per 1 revolution of a rotary encoder, occurs, prescale value is L/P.

E.g.) Positioning control by counter and encoder



[Diameter (D) of pulley connected with encoder= 22mm, the number of pulses by 1 rotation of encoder=1,000]

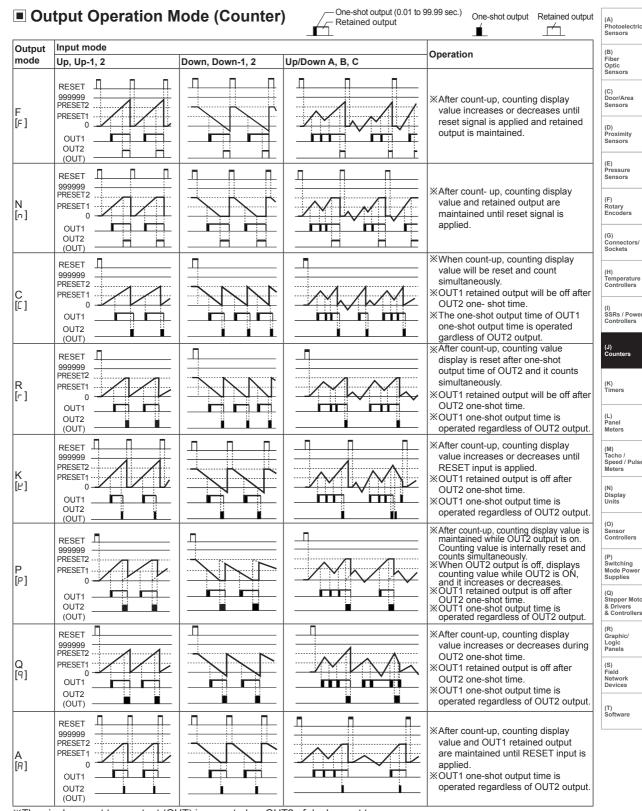
•Prescale value = $\frac{\pi \times \text{Diameter (D) of pulley}}{\text{The number of pulses by 1}}$ rotation of encoder = $\frac{3.1416 \times 22}{1000}$ = 0.069mm/pulse

Set decimal point[AP] as [-----], prescale decimal point [5EAP] as [-----], prescale value [5EL] as [0.069] at function setting mode. It is available to control conveyer position by 0.1mm unit.

Start Point Function (Counter)

This function is that start at initial value set at Start Point [5 + r +] when on counting mode.

- In case of dn, dn- 1 or dn- ≥ in timer input mode, it is not available.
- When reset is applied, the present value is initialized to start point.
- In case of £, r, P, q output operation mode, the present value starts at START POINT value after counting up.



^{**}The single preset type output (OUT) is operated as OUT2 of dual preset type.

^{*}OUT1 output could be set to 0 in all modes and 0 value output turns ON.

 $[\]times$ OUT2 output could not set to 0 in C[[], R[-], P[P] or Q[9] output mode.

Retained output Coincidence output Output Operation Mode (Counter) Output mode Up/Down - A, B, C Operation RESET 999999 **XOUT1** and OUT2 keep ON status in PRESET2 S PRESET1 following condition: 0 Counting display value ≧ PRESET1 [5] -99999 Counting display value ≥ PRESET2 OUT1 OUT2 (OUT) П RESET 999999 **XOUT1** output is off: PRESET2 Counting display value ≥ PRESET1 PRESET1 **XOUT2** keeps ON status in following [Ŀ] -99999 condition: OUT1 Counting display value ≥ PRESET2 OUT2 (OUT) RESET XWhen counting display value is equal 999999 to setting value [PRESET1, PRESET2) PRESET2 only, OUT1 or OUT2 output keeps ON PRESET1

- XThe single preset type output (OUT) is operated as OUT2 of dual preset type.
- ※The dual preset model OUT1 output is operated as one-shot or retained output. (except 5, ₺, ₼ mode)
- XOUT1 output could be set to 0 in all modes and 0 value output turns ON.
- \times OUT2 output could not set to 0 in C[[], R[-], P[P] or Q[9] output mode.

■ Counter Operation Of The Indicator (CT6S-I, CT6Y-I, CT6M-I)

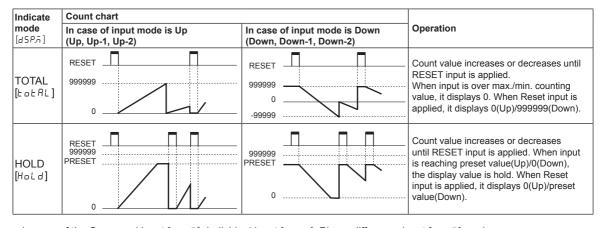
XOnly displays on indicator models

-99999

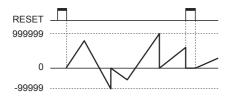
OUT1

OUT2

[6]



In case of the Command input [Ud-B], Individual input [Ud-b], Phase difference input [Ud-C] mode.



※In case of UP/DOWN [Ud-A, Ud-b, Ud-E] input mode, indication mode [d5P.n] of the configuration is not displayed.

When setting 1kcps for counting speed,

solid state contact output should be

used

J-22 Autonics

■ Parameter Setting (Timer)

(MD key: Moves the settings, ⋈, key: Changes the settings)

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(I) SSRs / Power Controllers

(N) Display Units

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

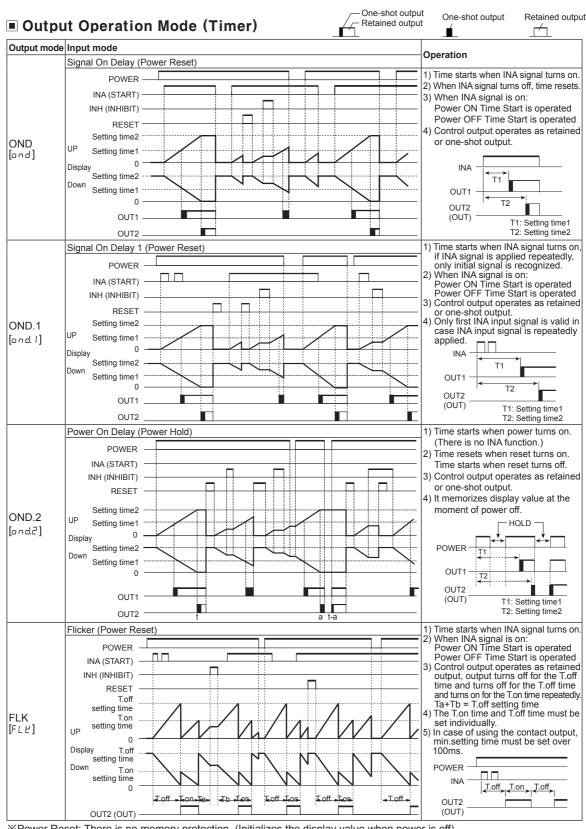
(R) Graphic/ Logic Panels

Parameter	Setting					
Counter/Timer	EoUn ← → ŁI ōE					
[[-+]	• 6-digit type					
	999999 ** 999999 ** 999999					
	0.001s to 0.01s to 0.1s to 0.01s to					
	999.99s 9999.9s 999999s 99m59.99s					
	Hour 5					
	999999 999599					
	0.1h to 0.1s to					
	99999.9h 999m59.9s					
T:						
Time range [HoUr/ō! n/5E[]	999959 995959 999999 999999 999959					
[100, 111, 112, 25, 2]	1m to 1s to 1m to 0.1m to 1s to					
	9999h59m 99h59m59s 999999m 99999.9m 9999m59s • 4-digit type					
	SEC SEC SEC 5					
	9999					
	0.001s to 0.01s to 1s to 1s to					
	9.999s 99.99s 999.9s 99m59s					
	1h to 1m to 0.1m to					
	XUB: Time progresses from '0' to the setting time					
Up/Down mode [U - d]	dn: Time progresses from the setting time to '0'.					
Indication mode	*Used for the indicator type only. **Wise added that the feature which set the setting.					
[d5P.ñ]	time when selecting HoLd or on E.d					
Memory protection	XUsed for the indicator type only.					
[9858]	Reset time value when power is oπ. rE[: Memorizes time value at the moment of power off.					
Output mode	and \rightarrow and $I \rightarrow$ and $Z \rightarrow$ FLY \rightarrow FLY. $I \rightarrow$ FLY. $Z \rightarrow$ I at					
[oUt.ā]	↑					
-						
OUT2 output time	Setting range: 00.01 to 99.99sec., Hold.					
[once]	When 1st digit is flashing, press the (key once and HoLd appears.					
OUT1 output time	XSet one-shot output time of OUT1.					
[oUt 1]**1	XWhen 1st digit is flashing, press the ⟨⟨ key once and HoLd appears.					
OLIT output time						
[o ii t.t.] *1						
Input logic						
[5: 6]	**Check input logic value (PNP, NPN).					
Input signal	/ ← → ≥□, ※CTS/CTY: Set min. width of INA, INH, RESET signal.					
time [/ n.t.]						
Key lock						
	L □ [.3 ← → L □ [.2] L □ [.3]: Locks RST, (€), (≥), (≥) keys, key lock indicator turns ON					
[JSP.n] Memory protection [JRLR] Output mode [JUL.n] OUT2 output time [JUL.n] OUT1 output time [JUL.n] OUT output time [JUL.n] Input logic [J.n.n] Input signal	## ## ## ## ## ## ## ## ## ## ## ## ##					

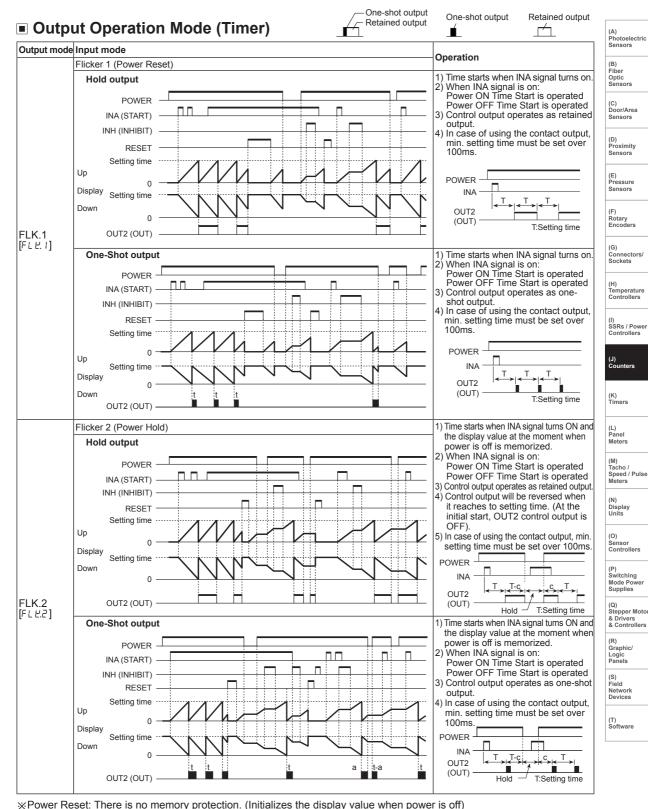
^{*1:} When output mode is FLE.1, FLE.2, I nE 0 and and, and.1, and.2 of 1-stage preset model, all 1 does not appear. The output time of all E2 is displayed as all E.E. When output mode is and, and I, and 2, I nE.2, all E1 appears.

J-23

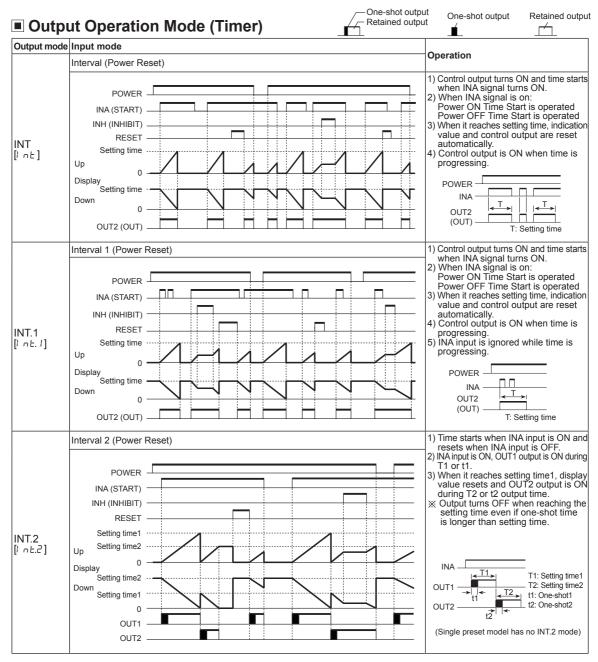
^{※2:} I n E.2 mode is available only for 2-stage preset model.



※Power Reset: There is no memory protection. (Initializes the display value when power is off) Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

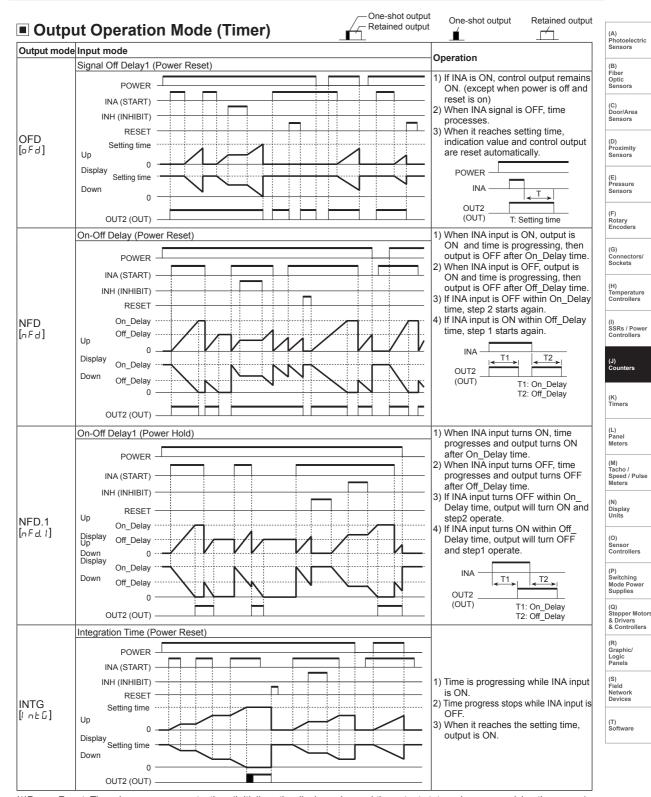


Power Hold: There is no memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)



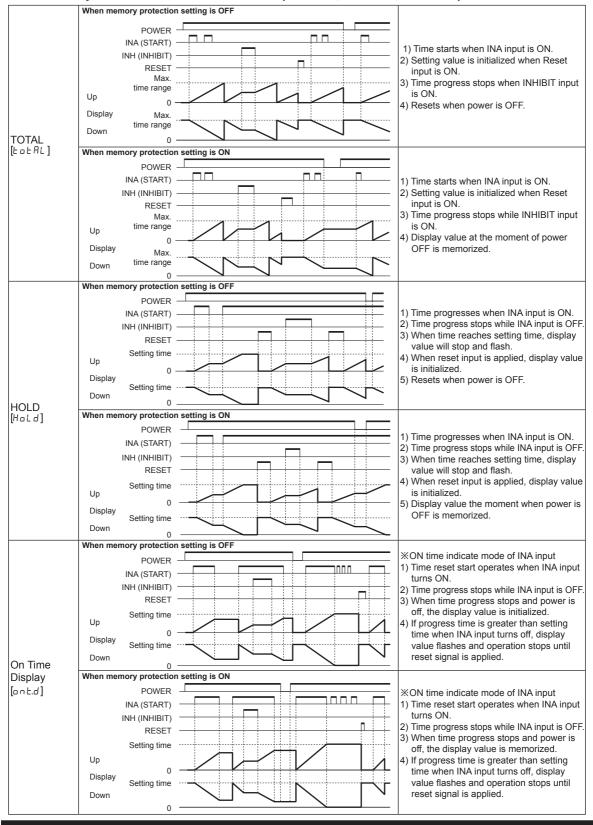
※Power Reset: There is no memory protection. (Initializes the display value when power is off)
Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

J-26 Autonics



※Power Reset: There is no memory protection. (Initializes the display value and the output status when re-supplying the power.)
Power Hold: There is memory protection. (It memorizes the status of power off. When re-supplying the power, it returns the memorized display value and the output status.)

■ Timer Operation Of The Indicator (CT6S-I, CT6Y-I, CT6M-I)



J-28 Autonics

- Timer '0' Time Setting
- Available output operation mode to set '0' time setting ond, ond. 1, ond.2, nFd, nFd. 1



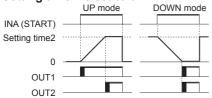
Retained output

One-shot output (0.01 to 99.99 sec.)

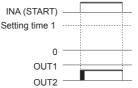
- Operation according to output mode (at 0 time setting)

1) OND (Signal ON Delay) mode [and]

Setting time1 is set to 0

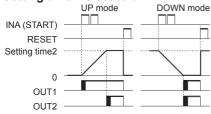


Setting time2 is set to 0



2) OND.1 (Signal ON Delay 1) mode [and. 1]

• Setting time1 is set to 0

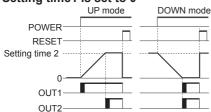


• Setting time2 is set to 0

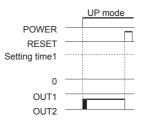


3) OND.2 (Power ON Delay2) mode [and.2]

• Setting time1 is set to 0

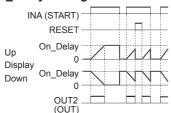


• Setting time2 is set to 0

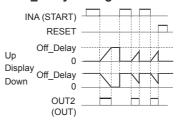


4) NFD (ON-OFF Delay) mode [nFd]

• OFF Delay setting time is set to 0

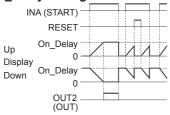


• ON Delay setting time is set to 0

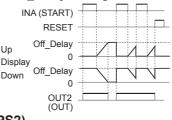


5) NFD.1 (ON-OFF Delay1) mode [nFd.1]

• OFF Delay setting time is set to 0



• ON Delay setting time is set to 0



Setting value1 (PS1) is higher than Setting value2 (PS2) OND[and], OND.1[and.1] or OND.2[and.2] output mode

• UP mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON.

• DOWN mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON. If the setting value 1 is same as the setting value2 and START signal is applied, OUT1 output turns ON immediately.

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity

(E) Pressure Sensors

(H) Temperature Controllers

(I) SSRs / Powe Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

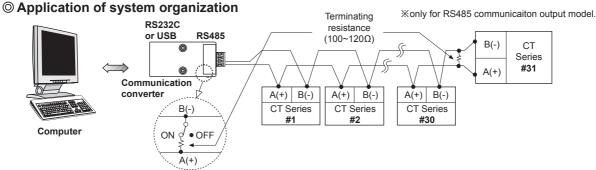
J-29 **Autonics**

Communication Mode

Parameter setting

(MD key: To select setting mode, ⋈ or key: To change setting value)

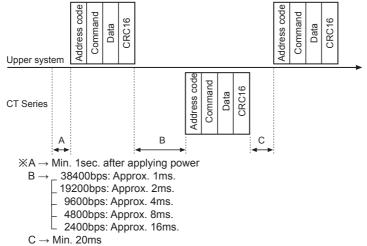
Setting mode	How to set					
Comm. address	 ▼ To shift flashing digits of Comm. address. ▼ S: To change the flashing digits. ★ Setting range of Comm. address: 1 to 127 ★ If the same address is applied during multiComm., it will not work correctly. 					
Comm. speed [b P 5]	24 ←→ 48 ←→ 96 ←→ 192 ←→ 384					
Comm. parity [アェヒリ]	nanE ← EuEn ← add					
Comm. stop bit [5 £ P]	1 ← → 2					
	Setting range according to comm. speed.					
	[▼]: To shift flashing digits position of 2400bps 16ms to 99ms					
esponse waiting time	Comm. response waiting time. 4800bps 8ms to 99ms					
[r 5 Y.E]	♥ ♠: To change the flashing digits 9600bps 5ms to 99ms					
	position value. 19200bps 5ms to 99ms					
	38400bps 5ms to 99ms					
Comm. write	EnR ← → dl 5R					



※It is recommended to use communication converter, RS485 to Serial converter (SCM-38I, sold separately),
USB to RS485 converter (SCM-US48I, sold separately). Please use a proper twist pair for RS485 communication.

O Communication control ordering

- 1. The communication method is Modbus RTU (PI-MBUS-300-REV.J).
- 2. After 1sec. of power supply into the high order system, it starts to communicate.
- Initial communication will be started by the high order system. When a command comes out from the high order system, CT Series will respond.



J-30 Autonics

© Communication command and block

The format of query and response

1) Read Coil Status (Func. 01 H), Read Input Status (Func. 02 H)

• Query (Master)

Slave Address	F	Starting Address				Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

• Response (Slave)

Slave Address	Function	Byte	Data	Data	Data	Error Check (CRC 16)	
Address		Count				Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

2) Read Holding Registers (Func. 03 H), Read Input Registers (Func. 04 H)

• Query (Master)

Slave Address	Function	Starting Address		No. of F		Error Ch (CRC 10	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
						1	

CRC 16

• Response (Slave)

Slave	Lunction	unction 5						Dala		Error Check (CRC 16)	
Address		Count	High	Low	High	Low	High	Low	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	

CRC 16

3) Force Single Coil. (Func 05 H)

Query (Master)

Slave Address		Coil Add	Address Force Data			Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
ī						i .	

CRC 16

Response (Slave)

	Slave Address	Function	Coil Address		Force D		Error Che (CRC 16)	
			High	Low	High	Low	Low	High
	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
-								

CRC 16

4) Preset Single Register (Func. 06 H)

• Query (Master)

Slave	Function	Registe Address		Preset [Data	Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
1-						ı	

CRC 16

• Response (Slave)

Slave		Register Address		Preset Data		Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

5) Preset Multiple Registers (Func. 10 H)

Query (Master)

Slave Address	Eunction	Starti Addre	Starting N Address F		f Byte Count			Data		Error Check (CRC 16)		
		High	Low	High	Low		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
la											1	

CRC 16

• Response (Slave)

Slave	Function	Starting A	Starting Address			Error Che (CRC 16)		
Address		High	Low	High	Low	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	

CRC 16

6) Application

Read Coil Status (Func. 01 H)
Master reads OUT2 00002 (0001H) to 00003
(0002H), OUT1 output status (ON: 1, OFF: 0) from
the Slave (Address 01).

Query (Master)

	.) (,					
Slave	Function	Starting A	Address	No. of Points Error Chec (CRC 16)			
Address		High	Low	High	Low	Low	High
01 H	01 H	00 H	01 H	00 H	02 H	EC H	0B H

On slave side OUT2 00003 (0002H): OFF, OUT1 00002 (0001H): ON

Response (Slave)

1	Slave Address	Function	Byte Count	Data	Error Check (CRC 16)	
Addres				00001)	Low	High
01 H		01 H	01 H	02 H	D0 H	49 H

Read Input Register (Func. 04 H)Master reads preset value 21004 (03EBH) to 21005 (03ECH) of counter/timer, Slave (Address 15).

• Query (Master)

- 1	Slave	Function	Starting A	Address			Error Check (CRC 16)	
	Address	T dilottoii	High	Low	High	Low	Low	High
	0F H	04 H	03 H	EB H	00 H	02 H	00 H	95 H

In case that the present value is 123456 (0001 E240 H) in slave side, 31004 (03EBH): E240 H, 31005 (03ECH): 0001H

• Response (Slave)

Slave	Function	Byte Count	Data		Data			Error Check (CRC 16)	
Address			High	Low	High	Low	Low	High	
0F H	04 H	04 H	E2 H	40 H	00 H	01 H	E2 H	28 H	

(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

> (J) Counters

...

(M) Tacho / Speed / Pulse Meters

Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

Field Network Devices

(T) Software

Modbus Mapping Table

1) Reset/Output

No. (Address)	Func.	Explanation	Setting	range	Notice
00001 (0000)	01/05	Reset	0:OFF	1:ON	_
00002 (0001)	01	OUT2 output	0:OFF	1:ON	_
00003 (0002)	01	OUT1 output	0:OFF	1:ON	_
00004 (0003)	01	BATCH output	0:OFF	1:ON	For BATCH output model
00005 (0004)	01/05	BATCH resets	0:OFF	1:ON	For BATCH output model

2) Terminal input status

No. (Address)	Func.	Explanation	Setting range	Notice
10001 (0000)	02	INA input status	0:OFF 1:ON	Terminal input status
10002 (0001)	02	INB input status	0:OFF 1:ON	Terminal input status
10003 (0002)	02	INHIBIT input status	0:OFF 1:ON	Terminal input status
10004 (0003)	02	RESET input status	0:OFF 1:ON	Terminal input status
10005 (0004)	02	BATCH RESET input status	0:OFF 1:ON	Terminal input status

3) Product Information

No. (Address)	Func.	Explanation	Notice
30001 to 30100	04	Reserved	_
30101 (0064)	04	Product number H	MadalID
30102 (0065)	04	Product number L	Model ID
30103 (0066)	04	Hardware version	_
30104 (0067)	04	Software version	_
30105 (0068)	04	Model no. 1	"CT"
30106 (0069)	04	Model no. 2	"6M"
30107 (006A)	04	Model no. 3	"-2"
30108 (006B)	04	Model no. 4	"PT"
30109 (006C)	04	Reserved	_
30110 (006D)	04	Reserved	
30111 (006E)	04	Reserved	_
30112 (006F)	04	Reserved	
30113 (0070)	04	Reserved	
30114 (0071)	04	Reserved	_
30115 (0072)	04	Reserved	_
30116 (0073)	04	Reserved	_
30117 (0074)	04	Reserved	
30118 (0075)	04	Coil Status Start Address	0000
30119 (0076)	04	Coil Status Quantity	_
30120 (0077)	04	Input Status Start Address	0000
30121 (0078)	04	Input Status Quantity	_
30122 (0079)	04	Holding Register Start Address	0000
30123 (007A)	04	Holding Register Quantity	
30124 (007B)	04	Input Register Start Address	0064
30125 (007C)	04	Input Register Quantity	_

4) Monitoring data

No. (Address)	Func.	Explanation	Setting range	Notice	
		BA.O LED display status	0:OFF 1:ON	Bit 5	
		OUT2 LED display status	0:OFF 1:ON	Bit 6	
		OUT1 LED display status	0:OFF 1:ON	Bit 7	
		BA.S LED display status	0:OFF 1:ON	Bit 10	
31001 (03E8)	04	LOCK LED display status	0:OFF 1:ON	Bit 11	
		PS2 LED display status	0:OFF 1:ON	Bit 12	
		PS1 LED display status	0:OFF 1:ON	Bit 13	
		TMR LED display status	0:OFF 1:ON	Bit 14	
		CNT LED display status	0:OFF 1:ON	Bit 15	
31002 (03E9)	04	Present value of BATCH	0 to 999999	For BATCH output	
31003 (03EA)	04	counter	0 10 333333	model	
31004 (03EB)			Counter 6digit type: -99999 to		
31005 (03EC)	04	Present value of counter/timer	999999 4digit type: -999 to 9999 Timer: Within time setting range	Use counter and timer in common	
31006 (03ED)	04	Display unit	Counter: decimal point of display value Timer: Time range	Counter: 40058 Data Timer: 40102 Data	
31007 (03EE)			Counter 6digit type: -99999 to	Use counter	
31008 (03EF)	04	PS (2) setting value	999999 4digit type: -999 to 9999 Timer: Within time setting range	and timer in common	
31009 (03F0)			Counter 6digit type: -99999 to	Use counter	
31010 (03F1)	04	PS1 setting value	999999 4digit type: -999 to 9999 Timer: Within time setting range	and timer in common	
31011 (03F2)	04	Setting value of BATCH	0 to 999999	Use counter and timer	
31012 (03F3)	U-T	counter		in common	
31013 (03F4)	04	Checking the input logic	0: NPN, 1: PNP		

• Date format of 31001 (03E8) address bit

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit4	Bit 3	Bit 2	Bit 1	Bit 0
CNT	TMR	PS1	PS2	LOCK	BA.S	_	_	OUT1	OUT2	BA.O	_	_	_	_	-
0 or 1	0	0	0 or 1	0 or 1	0 or 1	0	0	0	0	0					

※2 Words data format: Upper data has high number address.
E.g.)31004: Present Value (Low Word),
31005: Present Value (High Word)

5) Preset value setting group

No. (Address)	Func.	Explanation	Setting range	Notice
40001 (0000)	03	PS2 setting value	Counter	Use counter and timer
40002 (0001)	06 16	PS setting value	6digit type: 0 to 999999	in common
40003 (0002)	03	PS1 setting	4digit type: 0 to 9999 Timer: Within time	Use counter and timer
40004 (0003)	06 16	value	setting range	in common
40005 (0004)		BATCH	0 to 999999	Use counter
40006 (0005)	06 16	counter setting value	0 10 999999	and timer in common

J-32 Autonics

6) Function setting mode (Counter group)

No. (Address)	Func.	Explanation	Setting range	Notice
40051 (0032)	03/06/16	Counter/Timer [[-+]	1:CoUn 1:E!ñE	Use counter and timer in common
40052 (0033)	03/06/16	Input mode [! n]	0: UP 5: dn - 2 1: UP - 1 6: Ud - R 2: UP - 2 7: Ud - b 3: dn 8: Ud - E 4: dn - 1	_
40053 (0034)	03/06/16	Indication mode [dl 5 n]	O: ŁoŁAL 1: HoLd	For the indicator
40054 (0035)	03/06/16	Output mode [all E n]	0: F 3: r 6: 9 9: E 1: n 4: E 7: R 10: d 2: C 5: P 8: 5	_
40055 (0036)	03/06/16	Maximum counting speed [[P5]	0: 1	_
40056 (0037)	03/06/16	OUT2 (OUT) output time	000 l to 9999	unit: ×10ms
40057 (0038)	03/06/16	OUT1 Output time	000 l to 9999	unit: ×10ms
40058 (0039)	03/06/16	Decimal point [dP]	0: 2: 4: 1: 5:	4digit type 0: 1: 2: 3:
40059 (003A)	03/06/16	Min. reset time [-5]	0: / 1: 2 D	unit: ms
40060 (003B)	03/06/16	Prescale decimal point position [5 [L.d]	0: 3: 5: 2: 4:	4digit type 1: 2: 3:
40061 (003C) 40062 (003D)	03/06/16	Prescale value [5 £ L]	6digit type: 0.0000 to 999999 4digit type: 0.00 to 9999	Connected with prescale decimal point position
40063 (003E) 40064 (003F)	03/06/16	Start value [5 + r +]	6digit type: 000000 to 999999 4digit type: 0000 to 9999	Connected with decimal point position of display value
40065 (0040) 40066 (0041)	03/06/16	Memory protection [dRER] Lock key [LoCE]	0:[Lr 1:rE[0:LoFF 1:Lo[.] 2:Lo[.2 3:Lo[.3	Use counter and timer in common

7) Function setting mode (Timer group)

No. (Address)	Func.	Explanation	Setting range	Notice	
40101 (0064)	03/06/16	Counter/Timer[[-+]	0: CaUn 1: El ñE	Use counter and timer in common	
			4digit type		
		Time range [HoUr/hl n/5E[]	0: 0.001s to 9.999s 5: 0.1m to 999.9m 1: 0.01s to 99.99s 6: 1m to 9999m 2: 0.1s to 999.9s 7: 1m to 99h59m 3: 1s to 9999s 8: 1h to 9999h 4: 1s to 99m59s		
40102 (0065)	03/06/16		6digit type		
			0: 0.001s to 999.999s 6: 1s to 9999m59s 7: 1m to 99999.9m 2: 0.1s to 99999.9s 8: 1m to 999999m 9: 1s to 99959m 9: 1s to 99h59m59s 4: 0.01s to 99m59.9s 10: 1m to 9999h59m 5: 0.1s to 999m59.9s 11: 0.1h to 99999.9h		
40103 (0066)	03/06/16	UP/Down mode [U - d]	0: UP 1: dn	_	
40104 (0067)	03/06/16	Output mode [all E ñ]	0: ond 3: FLE 7: Int. I 10: nFd 1: ond I 4: FLE I 8: Int. 2 11: nFd I 2: ond 2 5: FLE 9: oFd 12: Int. G		
40105 (0068)	03/06/16	OUT2 (OUT) Output time	0000 to 9999 (0: Hold)	unit: ×10ms	
40106 (0069)	03/06/16	OUT1 Output time	0000 to 9999 (0: Hold)	unit: ×10ms	
40107 (006A)	03/06/16	Input signal time [I n E]	0: 1 1: 20	unit: ms	
40108 (006B)	03/06/16	Memory protection [dRLR]	0: ELr 1: r E E	Use counter and timer in common	
40109 (006C)	03/06/16	Lock key [Lo[P]	0: L.oFF 1: LoC. 2: LoC.2 3: LoC.3	Use counter and timer in common	
40110 (006D)	03/06/16	ndication mode [d 5 P.ñ]	O: totAL 1: Hold 2: ont.d	For the indicator	

(A) Photoelectric Sensors (C) Door/Area Sensors (D) Proximity Sensors (E) Pressure Sensors (H) Temperature Controllers (I) SSRs / Power Controllers (M) Tacho / Speed / Pulse Meters (P) Switching Mode Power Supplies (R) Graphic/ Logic Panels

8) Function setting mode (Communication group)

No. (Address)	Func.	Explanation	Setting range	Notice
40151 (0096)	03/06/16	Comm. address [Addr]	1 to 127	_
40152 (0097)	03/06/16	Comm. speed [b P 5]	0:24 1:48 2:96 3:192 4:384	unit: ×100bps
40153 (0098)	03/06/16	Comm. parity [Prty]	0:nonE 1:EuEn 2:odd	
40154 (0099)	03/06/16	Stop bit [5 £ P]	0: / 1: 2	
40155 (009A)	03/06/16	Response waiting time [-54.6]	05 to 99	unit: ms
40156 (009B)	03/06/16	Comm. writing [[añ.]]	0: EnR 1: d1 5R	_

© Exception processing

When communication error occurs, the highest bit of received function is set to 1, then sends response command and transmits exception code.

Slave Address	Function + 80H	Exception Code	Error Check (CRC16)		
Slave Address	T UTICUOTI + OUT	Lxception code	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	

- Illeegal Function (Exception Code: 01H): Not supporting command
- Illegal Data Address (Exception Code: 02H): Mismatch between the number of asked data and the number of ansmittable data.
- Illegal Data Value (Exception Code: 03H): Mismatch between asked the number of data and transmittable the number of data in device
- Slave Device Failure (Exception Code: 04H): Command is processed incorrectly.

Example)

Master reads output status (ON:1, OFF:0) of non existing coil 01001 (03E8 H) from Slave (Address17).

Query (Master)

Slave Address	Function	Starting Address		No. of Points		Error Check (CRC16)	
Slave Address		High	Low	High	Low	Low	High
11H	01H	03H	E8H	00H	01H	##H	##H

• Response (Slave)

Slave Address	Function + 80H	Exception Code	Error Check (CRC16)	
			Low	High
11H	81H	02H	##H	##H

Read And Write Of Parameter Value Using Communication

Read of the parameter area

00002 (OUT2), 00003 (OUT1), 00004 (BA, 0), 10001 to 10005 (Terminal input), 30101 to 30125 (Product information), 31001 to 31013 (Monitoring data)

Read and write of the parameter area

00001 (Reset starts), 00005 (BATCH Reset starts), 40001 to 40006 (Setting value saving group), 40051 to 40066 (Counter setting group), 40101 to 40110 (Timer setting group), 40151 to 40156 (Communication setting group)

Read of communication

Read parameter value using communication. (Function: 01H, 02H, 03H, 04H) It is able to read communication regardless of permitting/prohibiting communication writing.

Communication write

Change parameter value using communication. (Function: 05H, 06H, 10H)

- When changing the parameter setting value of '■ Function setting mode Counter group' or '■ Function setting mode
 Timer group' using communication, reset indication will flash in 3 sec. and display value will be reset. (Counting
 display value and progress time before changing parameter setting value are not saved.)
- When changing the parameter setting value of '
 Preset value setting group' or '
 Function setting mode
 Communication group' using communication, counting display value or progress time will not be reset.
- In prohibit writing communication setting (E □ Ā. ੁ = 1: d | 5 A), a write command does not process.
- If setting value beyond the setting range, this setting value is substituted for the value within the setting range and then memorized.

J-34 Autonics

■ Factory Default

	Parameter	Factory default
		-
Counter	In	Ud-C
	oUt.ñ	F
	d5P.ñ	totAL
	CP5	30
	oUt 2 (oUt.t)	Hold (fixed)
	oUE I	00.10
	dР	
	r5t	20
	51 0	nPn
	SC.dP	6-digit type:
	31.07	4-digit type:
	SCL	6-digit type: 1.00000
		4-digit type: 1.000
	Strt	000000
	dRER .	ELr
	HoUr/ñ! n/5EC	6-digit type: 0.00 /s-999.999s 4-digit type: 0.00 /s-9.999s
	U - d	UP
	d5P.ñ	t o t A L
T:	dR ER	ELr
Timer	oUt.ñ	ond
	oUt 2 (oUt.t)	HoLd
	oUt I	00.10
	51 0	nPn
	I n.t	20
	LoCY	L.of F
General	PS1	1000
	PS2	5000
	Rddr	001
	6P5	96
	Prty	nonE
Comm.	5 L P	2
	r52F	20
	Coñ.Y	EnR

Cautions During Use

O Power ON/OFF



- The inner circuit voltage rises within 100ms after supplying the power to the unit. The input is unavailable at this period. Be sure that the inner circuit voltage drops within 500ms after turning OFF the power.
- O In case of 24VAC / 24-48VDC model, power supply should be insulated and limited voltage/current or Class 2 power supply device.

O Input signal line

- Shorten the cable from the sensor to the unit.
- Use shield cable when input cable is longer.
- Wire the input signal line separately from power line.

⊚ Input logic selection

Before selecting input logic, must cut off the power to counter/timer. Select the input logic following the instruction.

© Contact counting input (counter operation)

If apply contact input at high speed mode (1k, 5k, 10kcps), it may cause miscount by chattering.

Therefore set low speed mode (1cps or 30cps) at contact.

Therefore set low speed mode (1cps or 30cps) at contact input.

Testing dielectric voltage or insulation resistance when the unit is installed at control panel

- Isolate the unit from the circuit of control panel.
- Short all terminals of the unit

O Do not use the unit in the following environments.

- Environments with high vibration or shock.
- · Environments with strong alkali or strong acid materials
- Environments with exposure to direct sunlight
- Near machinery which produce strong magnetic force or electric noise

This product may be used in the following environments.

- Indoor
- Max. altitude: 2,000m
- Pollution degree 2
- Installation category II

(A)
Photoelectric
Sensors

(B)
Fiber
Optic
Sensors

(C)
Door/Area
Sensors

(D) Proximity Sensors (E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

Counters

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies (Q) Stepper Motors

Stepper Motor & Drivers & Controllers

(R) Graphic/ Logic Panels

Field Network Devices

(T) Software