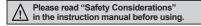
## Shaft type Ø50mm Magnetic Single-turn Absolute Rotary Encoder

#### Features

- Higher resistant to vibration and impact by magnetic elements than optical encoder
- Various output code: BCD, Binary, Gray code
- Various and high resolution
  - (32, 40, 45, 48, 64, 90, 128, 180, 256, 360, 512, 720, 1024-division)
- Power supply: 5VDC ±5%, 12-24VDC ±5%
- Protection structure IP50 (IEC standard)







CONTROLLERS

MOTION DEVICES

SOFTWARE

SENSORS

## Ordering Information

MGA50S	8	1024	- 1	R -	- N -	- 5	
Series	Shaft diameter	Pulses/revolution	Output code	Revolution direction	Control output	Power supply	
Ø50mm shaft type	Ø8mm	Refer to resolution	1: BCD code	F: Output value increase at CW direction R: Output value increase at CCW direction		5: 5VDC ±5% 24: 12-24VDC ±5%	

Specifications

Туре		Shaft Type Ø50mm Magnetic Single-turn Absolute Rotary Encoder										
Model		MGA50S8N										
Reso	Resolution <sup>*1</sup>		32, 40, 45, 48, 64, 90, 128, 180, 256, 360, 512, 720, 1024-division									
		Hysteresis	±0.1°									
		Positioning error*2	±1-bit (LS	B: Least Significant Bit)								
		Output code	Division	BCD code	Binary code	Gray code						
			1024	TS: 0.3515°±15' (13-bit)	TS: 0.3515°±15' (10-bit)	TS: 0.703°±15' (10-bit)						
			720	TS: 0.5°±25' (11-bit)	TS: 0.5°±25' (10-bit)	TS: 1°±25' (10-bit)						
			512	TS: 0.703°±25' (11-bit)	TS: 0.703°±25' (9-bit)	TS: 1.406°±25' (9-bit)						
			360	TS: 1°±25' (10-bit)	TS: 1°±25' (9-bit)	TS: 2°±25' (9-bit)						
			256	TS: 1.406°±25' (10-bit)	TS: 1.406°±25' (8-bit)	TS: 2.8125°±25' (8-bit) TS: 4°±25' (8-bit) TS: 5.625°±25' (7-bit) TS: 8°±25' (7-bit)						
			180	TS: 2°±25' (9-bit)	TS: 2°±25' (8-bit)							
			128	TS: 2.8125°±25' (9-bit)	TS: 2.8125°±25' (7-bit)							
ے			90	TS: 4°±25' (8-bit)	TS: 4°±25' (7-bit)							
Electrical specification Output	utput		64	TP1: 4.5°±60' (1-bit) TP2: 1.125°±60' (1-bit) TS: 5.625°±60' (7-bit) EP: 5.625°±60' (1-bit)	TP1: 4.5°±60' (1-bit) TP2: 1.125°±60' (1-bit) TS: 5.625°±60' (6-bit) EP: 5.625°±60' (1-bit)	TP1: 4.5°±60' (1-bit) TP2: 1.125°±60' (1-bit) TS: 11.25°±60' (6-bit) EP: 5.625°±60' (1-bit)						
	Ō	Output phase/ Output angle <sup>※3</sup>	48	TP1: 6°±60' (1-bit) TP2: 1.5°±60' (1-bit) TS: 7.5°±60' (7-bit) EP: 7.5°±60' (1-bit)	TP1: 6°±60' (1-bit) TP2: 1.5°±60' (1-bit) TS: 7.5°±60' (6-bit) EP: 7.5°±60' (1-bit)	TP1: 6°±60' (1-bit) TP2: 15°±60' (1-bit) TS: 1.5°±60' (6-bit) EP: 7.5°±60' (1-bit)						
			45	TP1: 6.4°±60' (1-bit) TP2: 1.6°±60' (1-bit) TS: 8°±60' (7-bit) EP: 8°±60' (1-bit)	TP1: 6.4°±60' (1-bit) TP2: 1.6°±60' (1-bit) TS: 8°±60' (6-bit) EP: 8°±60' (1-bit)	TP1: 6.4°±60' (1-bit) TP2: 1.6°±60' (1-bit) TS: 16°±60' (6-bit) EP: 8°±60' (1-bit)						
			40	TP1: 7.2°±60' (1-bit) TP2: 1.8°±60' (1-bit) TS: 9°±60' (6-bit) EP: 9°±60' (1-bit)	TP1: 7.2°±60' (1-bit) TP2: 1.8°±60' (1-bit) TS: 9°±60' (6-bit) EP: 9°±60' (1-bit)	TP1: 7.2°±60' (1-bit) TP2: 1.8°±60' (1-bit) TS: 18°±60' (6-bit) EP: 9°±60' (1-bit)						
			32	TP1: 9°±60' (1-bit) TP2: 2.25°±60' (1-bit) TS: 11.25°±60' (6-bit) EP: 11.25°±60' (1-bit)	TP1: 9°±60' (1-bit) TP2: 2.25°±60' (1-bit) TS: 11.25°±60' (5-bit) EP: 11.25°±60' (1-bit)	TP1: 9°±60' (1-bit) TP2: 2.25°±60' (1-bit) TS: 22.5°±60' (5-bit) EP: 11.25°±60' (1-bit)						

X1: Not indicated resolutions are customizable.

※2: When turning ON/OFF the unit, there may be ±1-bit (LSB) error at present position by hysteresis.

X3: TP1, TP2 other output angles are available as option.

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

> G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

Autonics H-75

## **MGA50S Series**

## Specifications

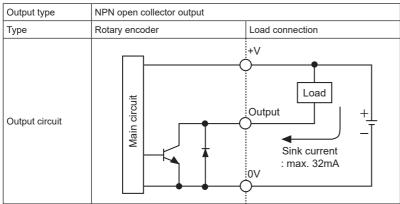
Туре			Shaft Type Ø50mm Magnetic Single-turn Absolute Rotary Encoder							
Mod	el		MGA50S8							
		Output type	NPN open collector output							
	Ħ	Output capacity	Load current max. 32mA, residual voltage max. 1VDC==							
l iol	Output	Output logic	Negative logic output							
specification	0		Max. 1μs (cable length: 2m, I sink=32mA)							
sbe	Ма	x. response frequency	30kHz							
<del> </del>	Po	wer supply	5VDC== ±5% (ripple P-P: max. 5%), 12-24VDC== ±5% (ripple P-P: max. 5%)							
Electrical	Cu	rrent consumption	Max. 60mA (disconnection of load)							
	Ins	ulation resistance	Over $100M\Omega$ (at $500VDC$ megger between all terminals and case)							
- [	Die	electric strength	750VAC 50/60Hz for 1 min (between all terminals and case)							
	Co	nnection	Axial cable type (cable gland)							
la la	5 S		Max. 70gf·cm (0.007N·m)							
anic	ğΓ	Moment of inertia	Max. 80g·cm² (8×10 <sup>-6</sup> kg·m²)							
Mechanical	S S	Shaft loading	Radial: max. 10kgf, Thrust: max. 2.5kgf							
₩ ď	5 N	Max. allowable revolution**4	3,000rpm							
Vibra	atio	n	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours							
Shoo	ck		Approx. max. 75G							
Envi	ron	- Ambient temperature	-10 to 70°C, storage: -25 to 85°C							
men	t	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH							
Prote	ecti	on structure	IP50 (IEC standard)							
Cabl			Ø6mm, 17-wire, 2m, Shield cable (AWG 28, core diameter: 0.08mm, number of cores: 17, insulator diameter: Ø0.8mm)							
Acce	2886	orv	Bracket, Coupling							
Appi			C €							
<u> </u>			Approx. 400g (approx. 270g)							
Weight <sup>#5</sup>			7 Approx. 400g (approx. 210g)							

Resolution

35: The weight includes packaging. The weight in parenthesis is for unit only.

XEnvironment resistance is rated at no freezing or condensation.

# **■** Control Output Circuit



\*The output of each bit is same circuit.

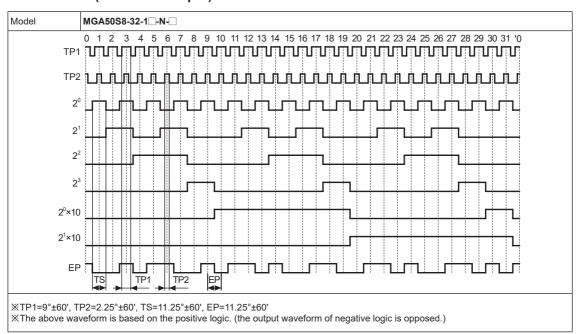
\*Be sure that when applying excessive load or being short, the circuit may be damaged.

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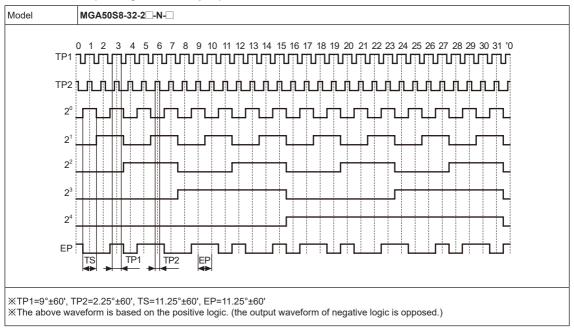
# Absolute Ø50mm Magnetic Single-turn Shaft Type

## Output Waveform

#### 32-division (BCD code output)



## ○ 32-division (Binary code output)



**Autonics** 

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CONTROLLERS

MOTION DEVICES

SENSORS

SOFTWARE

(A) Photoelectric

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

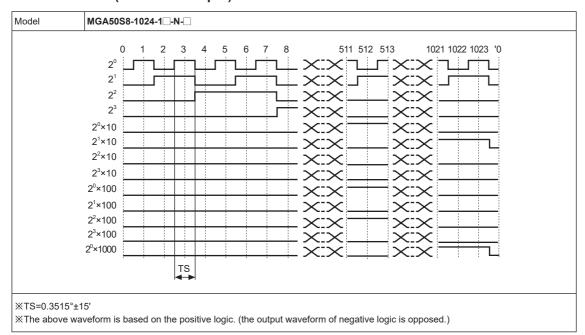
(G) Pressure Sensors

(H) Rotary Encoders

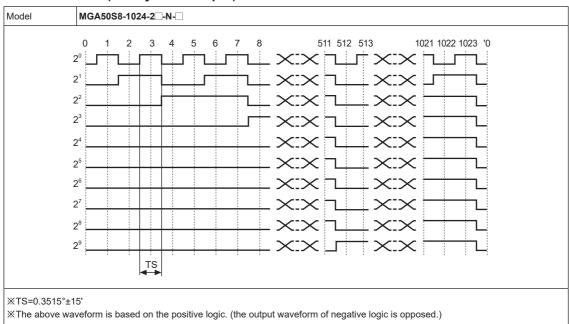
Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

## Output Waveform

#### ○ 1024-division (BCD code output)



#### ○ 1024-division (Binary code output)



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# Absolute Ø50mm Magnetic Single-turn Shaft Type

### Connection

#### O BCD code

	Resolution		40	45	48	64	90	128	180	256	360	512	720	1024	
Color		-division	-division	-division	-division	-division	-division	-division	-division	-division	-division	-division	-division	-division	
White +V															
Power	Black							0V							
	Brown		20												
	Red		21												
	Orange		2 <sup>2</sup>												
	Yellow		2 <sup>3</sup>												
	Green		2°×10												
	Blue		2 <sup>1</sup> ×10												
<u>e</u>	Purple	N	·C						2 <sup>2</sup> ×10						
t cab	Gray			TP1				2 <sup>3</sup> ×10							
Output cable	Pink			TP2			N-C 2°×100								
ő	Transparent			EP				N·C 2 <sup>1</sup> x·							
	Light Brown	N·C 2 <sup>2</sup> ×100													
	Light Yellow	N-C 2 <sup>3</sup> ×10										2 <sup>3</sup> ×100			
	Light Green	N·C 2º×1000											2°×1000		
	Light Blue							N⋅C							
	Light Purple							N⋅C							
Shield cable Signal shield ca										(F.G.)					

#### Binary Code/Gray code

Resolution			40	45		64	90	128	180	256	360	512	720	1024		
Colo	or	-division	-division	-division	-division	-division	-division	-division	-division	-division	-division	-division	-division	-division		
Power	White							+V								
Po	Black	0V														
	Brown	2º														
	Red	21														
	Orange	22														
	Yellow	23														
	Green	24														
	Blue	N·C 2 <sup>5</sup>														
<u>e</u>	Purple	N-C							2 <sup>6</sup>							
Output cable	Gray			TP1			N	N·C 2 <sup>7</sup>								
ntbn	Pink	TP2						N-C					28			
Ō	Transparent	EP						N·C 2 <sup>9</sup>						2 <sup>9</sup>		
	Light Brown	N⋅C														
	Light Yellow	N-C														
	Light Green							N-C								
	Light Blue							N·C								
	Light Purple		N·C													
	Shield cable						Signal	shield cab	le (F.G.)							

XNon-using wires must be insulated.

SENSORS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LiDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

> l) otary

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

Autonics H-79

XEncoder case and shield cable must be grounded.

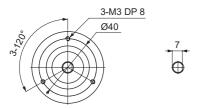
<sup>※</sup>N·C (not connected)

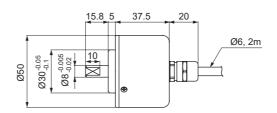
<sup>\*\*</sup>Please make sure not to short when wiring output cables because the dedicated driver IC is used at output circuit.

<sup>\*</sup>Do not apply tensile strength over 30N to the cable.

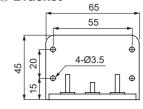
### Dimensions

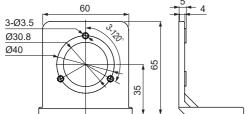
(unit: mm)



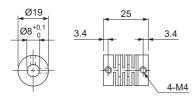


#### O Bracket





## O Coupling



- Parallel misalignment: max. 0.25mm
- Angular misalignment: max. 5°
- End-play: max. 0.5mm
- XDo not put strong impact when insert a coupling into shaft. Failure to follow this instruction may result in product damage.
- % Fix the unit or a coupling by a wrench under 0.15 N⋅m of torque.
- When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit.
- \*\*For parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description.
- \*\*For flexible coupling (ERB series) information, refer to the ERB series section.

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