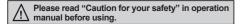
Features

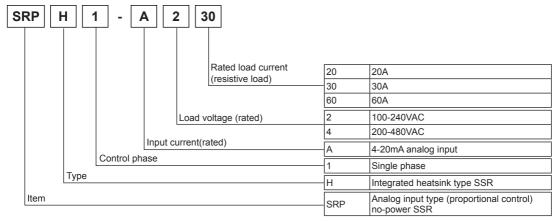
- Power control/ Cycle control/Phase control (fixed cycle/ variable cycle) are available with 4-20mA analog input
- Superior dielectric strength: 4,000VAC
- Improved reliability by maximizing heat protection efficiency with heatsink integrated design and ceramic board
- Various mounting methods (DIN rail, panel front)
- Checks input status by Input LED (green)







Ordering Information



Model	Rated load current	Load voltage
SRPH1-A220	20A	
SRPH1-A230	30A	100-240VAC
SRPH1-A260	60A	

Model	Rated load current	Load voltage
SRPH1-A420	20A	
SRPH1-A430	30A	200-480VAC
SRPH1-A460	60A	

Specifications

O Input

~ ··· /- ···			
4-20mA analog input			
Max. allowable input current	50mA		
Pick-up current	4.2mA		
Static off current	0.2mA		
Power factor	Min. 0.9 (max. 25° of difference between voltage phase and current phase)		
Input LED	Green		
Start-up time	60Hz: 200ms, 50Hz: 250ms		
Operation time	60Hz: 16.6ms, 50Hz:20ms		
Operation mode ^{*1}	Cycle control (fixed cycle, variable cycle) Phase control (phase equality division type, power equality division type)		

X1: You can change operation mode by jumper pin. Default is Phase control (Power equality division type).

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Specifications

Output

100-240VA	C load voltage				
Load voltage	range (50/60Hz)	90-264VACrms			
Rated load current Ta=25°C	Resistive load (AC-51)	20Arms	30Arms	60Arms	
Min. load cu	rrent	0.5Arms	·	·	
Max. 1 cycle (60Hz)	surge current	300A	500A	1000A	
Max. non-re current (l ² t, t	petitive surge =8.3ms)	350A ² S	1000A ² S	4000A ² S	
Peak voltage	e (Non-repetitive)	600V		·	
	Hz, Ta=25°C)	Max. 10mArms			
Output ON voltage drop[Vpk] (max. load current)		Max. 1.6V			
Static off state dv/dt		500V/μs	500V/μs		
200-480VA	C load voltage				
Load voltage	range (50/60Hz)	200-528VACrms			
Rated load current	Resistive load (AC-51)	20Arms	30Arms	60Arms	
Ta=25°C	Motor load (AC-53a)	5Arms	8Arms	15Arms	
Min. load cu	rrent	0.5Arms			
Max. 1 cycle (60Hz)	surge current	300A	500A	1000A	
Max. non-repetitive surge current (I²t, t=8.3ms)		350A ² S	1000A ² S	4000A ² S	
Peak voltage	e (non-repetitive)	1000V		·	
Leakage cur (480VAC/60	rent Hz, Ta=25°C)	Max. 10mArms			
Output ON voltage drop [Vpk] (Max. load current)		Max. 1.6V			
[vpk] (iviax.	ioda odironti				

General Specifications

Certification		UL508, CSA22.2 No.14, IEC/EN 60947-4-3	
		01000, 007/22.2 NO. 17, 120/21N 0007/ 7 0	
Phase control		5 to 99%	
	uality division type)		
Phase control		10 to 99%	
(power equ	uality division type)	10 to 99 %	
Frequency reading function		Yes	
Dielectric strength (Vrms)		4000VAC 50/60Hz for 1min. (Input-Output, Input/Output-Case)	
Insulation resistance		Min. 100MΩ (at 500VDC megger)	
Vibration		10 to 55Hz double amplitude 0.75mm in each X, Y, Z direction for 1 hour	
	Ambient temperature	-20 to 70°C, storage : -20 to 100°C	
Environ		(The rated load current capacity is different depending on ambient temperature.	
-ment		Refer to 🔳 SSR Characteristic Curve'.)	
	Ambient humidity	45 to 85%RH	
Input termi	nal connection	Min. 1×0.5mm² (1×AWG20) Max. 1×1.5mm² (1×AWG6) or Max. 2×1.5mm² (2×AWG16)	
Output terminal connection		Min. 1×1.5mm² (1×AWG16) Max.1×16mm² (1×AWG6) or Max. 2×6mm² (2×AWG10)	
		**Connect appropriate cable for the load current capacity to output terminal.	
Input terminal fixed torque		0.75 to 0.95N·m	
Output terminal fixed torque		1.6 to 2.2N·m	
Unit weight		• SRPH1-A220, SRPH1-A230, SRPH1-A420, SRPH1-A430 : Approx. 410g • SRPH1-A260, SRPH1-A460 : Approx. 680g	

XFor wiring the terminal, an O-ring terminal must be used.

(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

Sensors

(F) Rotary Encoders

Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J)

K) imers

L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

> (O) Sensor

Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T)

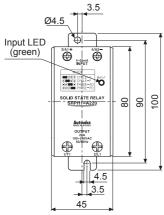
Autonics I-19

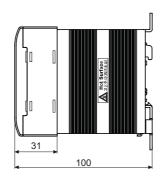
X Environment resistance is rated at no freezing or condensation.

■ Dimensions & Mounting

O Dimensions

• 20A/30A rated load current



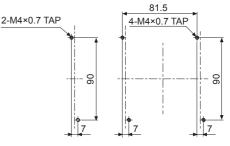


O Hole cut-out for panel front mounting

20A/30A rated load current

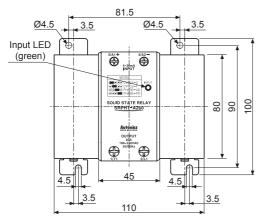
60A rated load current

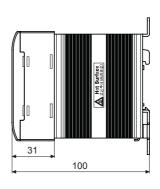
(unit: mm)



XTightening torque for mounting: 1.8 to 2.5N⋅m

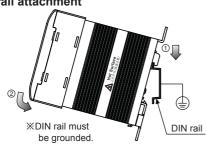
• 60A rated load current

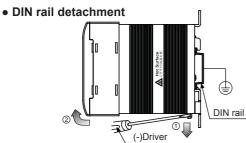




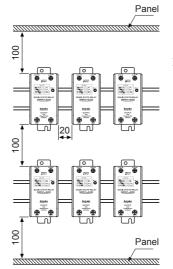
O DIN rail mounting

DIN rail attachment





Installation interval



※For mounting multiple SSR, please keep certain installation intervals for heat prevention.

For horizontal installation (when the heights of input part and output part are equal), it is recommended to apply 50% of rated load current.

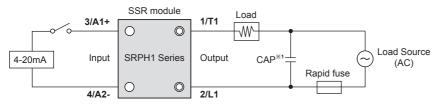
High temperature caution

Make sure do not touch the heat sink or the unit body while power is supplied or right after load power is turned off.

If not, it may cause a burn.

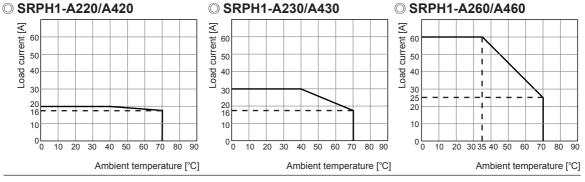
I-20

Connections



※1: As above connection, connect a capacitor. It is proper to EMC.
CAP: Load voltage 100-240VAC → 1uF/250VAC, Load voltage 200-480VAC → 0.47uF/500VAC

■ SSR Characteristic Curve



Operation Setting

• Detach front cover

Press front cover connection 4 parts at right and left side with (-) driver, and front cover is detached. **Before detaching front cover, you must cut off load

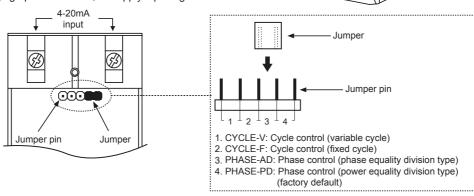
Eerore detacning front cover, you must cut off load current and input.

Flat head (-) driver

• Jumper pin setting

Operation mode is decided by jumper position.

After changing operation mode, re-supply input signal.



(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

Encoders

Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

Counters

(K) Timers

(L) Panel

(M) Tacho / Speed / Pulse

(N) Display Units

> (O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

T)

Autonics I-21

SRPH1 Series

Operation Mode

O Phase control

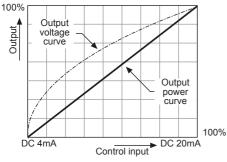
Output waveform of phase control

• When control input signal is 25% • When control input signal is 50% • When control input signal is 75%



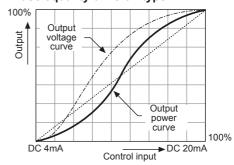
X1: The black parts of output waveform are output on the load.

• Power equality division type



Controls output power which is proportional to control input (4-20mA) level.

• Phase equality division type



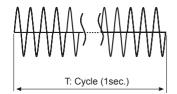
Controls phase angle which is proportional control input (4-20mA) level.

Cycle control

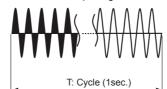
• Fixed cycle

Controls continuously the number of full cycle which is supplied to load every 1sec. by being proportional to control input (4-20mA).

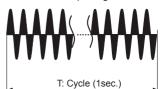
• When control input signal is 0%



· When control input signal is 50%



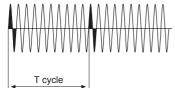
When control input signal is 100%



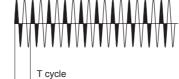
• Variable cycle

Controls fast and accurately the subject with optimized the number of AC voltage cycle which is supplied to load by being proportional to control input (4-20mA).

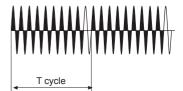
When control input signal is 10%



· When control input signal is 50%



When control input signal is 90%



Proper Usage

M High temperature caution

Make sure do not touch the heat sink or the unit body while power is supplied or right after load power is turned off. If not, it may cause a burn.

Caution for using

- 1. Attach a heatsink and ventilate for smooth convection current. If not, congested heat transfer may cause product failure or malfunction.
- 2. For mounting multiple SSR, please keep certain installation intervals for heat prevention. For horizontal installation (when the heights of input part and output part are equal), it is recommended to apply less than 50% of the rated load current.
- 3. Make sure do not touch the heatsink or the unit body while power is supplied or right after load power is turned OFF. If not, it may cause a burn.
- 4. Connect the proper cable for the rated load current with output terminal.
- 5. Use rapid fuse of which I2t is under 1/2 of SSR I2t in order to protect the unit from load's short- circuit current.
- 6. In case of a short-circuit please replace the fuse with a 1/2 of SSR I²t value specified semiconductor protective type.
- 7. In case that load's current is lower than SSR min. load current, connect dummy resistance to the load in parallel so as to make load's current higher than SSR min. load current.
- 8. Make sure that the screw on output terminal is tightly fastened. Using the unit with loose bolt may cause product failure or malfunction
- 9. Do not touch the load's terminal even if output is OFF. It may cause electric shock.
- 10. The input of the 4-20mA should be supplied by the insulated and limited voltage/current or by class 2 power supply.
- 11. Proper application environment (Avoid following environments to install)
- ① Where temperature/humidity is beyond the specification
- ② Where dew condensation occurs due to temperature change
- ③ Where inflammable or corrosive gas exists
- Where direct rays of light exist
- (5) Where severe shock, vibration or dust exists
- (6) Where near facilities generating strong magnetic forces or electric noise
- 12. This product may be used in the following environments.
- 1) Indoor
- 2 Altitude: Under 2,000m
- ③ Pollution Degree 2
- 4 Installation Category III

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity

(E) Pressure Sensors

(I) SSRs / Powe Controllers

(M) Tacho / Speed / Pulse Meters

(P) Switching Mode Power Supplies

(Q) Stepper Motors

Logic Panels

I-23 **Autonics**